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Autor(en): Meyerhoff, Robert

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# Sphere-packing and volume in hyperbolic 3-space 

Robert Meyerhoff ${ }^{(1)}$

## I. INTRODUCTION

A hyperbolic 3-manifold is a Riemannian manifold of constant sectional curvature -1 . We will restrict our attention to complete orientable hyperbolic 3-manifolds $M$; as such, we can think of $M$ as $H^{3} / \Gamma$ where $\Gamma$ is a discrete torsion-free subgroup of Isom $_{+}\left(H^{3}\right)$, the orientation-preserving isometries of hyperbolic 3-space. We will generally work in the upper-half-space model $H^{3}$ of hyperbolic 3-space, in which case $\operatorname{PGL}(2, \mathbf{C})$ acts as orientation-preserving isometries on $H^{3}$ by extending the action of $\operatorname{PGL}(2, \mathbf{C})$ on the Riemann sphere (boundary of $H^{3}$ ) to $H^{3}$. An orbifold is a space locally modelled on $\mathbf{R}^{n}$ modulo a finite group action. Complete orientable hyperbolic 3 -orbifolds $Q$ correspond to discrete subgroups $\Gamma$ of $P G L(2, \mathbf{C})$. If the discrete group $\Gamma$ corresponding to $M$ or $Q$ has parabolic elements then $M$ or $Q$ is said to be cusped.

Unless otherwise stated, we will assume all manifolds and orbifolds are orientable. Mostow's theorem implies that a complete, hyperbolic structure on a 3 -orbifold of finite volume is unique. Consequently, hyperbolic volume is a topological invariant for orbifolds admitting such structures. Jørgensen and Thurston proved (see [T] section 6.6) that the set of volumes of complete hyperbolic 3 -manifolds is well-ordered and of order type $\omega^{\omega}$. In particular, there is a complete hyperbolic 3 -manifold of minimum volume $V_{1}$ among all complete hyperbolic 3-manifolds, and a cusped hyperbolic 3-manifold of minimum volume $V_{\omega}$. Further, all volumes of closed manifolds are isolated, while volumes of cusped manifolds are limits from below (thus the notation $V_{\omega}$ ).

Modifying the proofs in the Jørgensen-Thurston theory yields similar results for complete hyperbolic 3-orbifolds (this result is folklore, and we will not prove it here). In particular, there is a hyperbolic 3-orbifold of minimum volume $V_{1}^{\prime}$, and a cusped hyperbolic 3 -orbifold of minimum volume $V_{c}^{\prime}$.

[^0]In [M1] and [M2] it is proved that

$$
\begin{aligned}
0.00064 & <V_{1} \leq \operatorname{vol}\left(M_{(5,1)}\right) \approx 0.98 \\
\sqrt{3} / 4 & \leq V_{\omega} \leq \operatorname{vol}\left(S^{3}-\text { figure-eight knot }\right)=2 V \approx 2.02988 \\
0.0000013 & <V_{1}^{\prime} \leq 2 \cdot \operatorname{vol}(0=0) \approx 0.072 \\
\sqrt{3} / 24 & \leq V_{c}^{\prime} \leq \operatorname{vol}\left(H^{3} / P G L_{2}\left(\mathcal{O}_{3}\right)\right)=V / 12 \approx 0.0846
\end{aligned}
$$

where $M_{(5,1)}$ is the manifold obtained by performing $(5,1)$ Dehn surgery on the figure-eight knot in the 3 -sphere, $V$ is the volume of the ideal regular tetrahedron in $H^{3}, \cong=0$ denotes the (non-orientable) tetrahedral orbifold with that Coxeter diagram (see [T] theorem (13.5.3)), and $\mathbb{O}_{3}$ is the ring of integers in $\mathbf{Q}(\sqrt{-3})$.

The left-hand inequalities of all of these estimates can be improved by using sphere-packing arguments. In this paper we prove,

$$
\begin{aligned}
0.00082 & <V_{1} \leq 0.98 \ldots{ }^{(2)} \\
V / 2 & \leq V_{\omega} \leq 2 V^{(3)} \\
0.0000017 & <V_{1}^{\prime} \leq 0.07177 \ldots \\
V / 12 & \leq V_{c}^{\prime} \leq V / 12
\end{aligned}
$$

From the last set of inequalities we see $V_{c}^{\prime}=V / 12$, i.e.
THEOREM. The orbifold $Q_{1}=H^{3} / P G L_{2}\left(O_{3}\right)$ has minimum volume among all orientable cusped hyperbolic 3 -orbifolds.

NOTE. $Q_{1}$ is the orientable double-cover of the (non-orientable tetrahedral orbifold with Coxeter diagram a-0. $\overline{\text { O }} 0$ (see $[\mathrm{H}]$ section 1 ). This tetrahedral orbifold has fundamental domain $1 / 24$ of the ideal regular hyperbolic tetrahedron (use the symmetries). In particular, $Q_{1}$ has a cusp and its volume is $1 / 12$ the volume of the ideal regular tetrahedron, i.e. $\operatorname{vol}\left(Q_{1}\right)=V / 12 \approx 0.0846$.

Remark. The four right-hand inequalities above are simply a list of the lowest volume orbifolds and manifolds of the various types known to date. These volumes are computed by decomposing the orbifold or manifold into hyperbolic

[^1]tetrahedra and then using Lobachevsky's formula to compute the volumes of these tetrahedra (see [ T ] chapter 7 for the case of ideal hyperbolic tetrahedra, and [La] for the case of non-ideal tetrahedra - actually, these tetrahedra must be further decomposed into "doubly-rectangular" tetrahedra). The decomposition into tetrahedra for tetrahedral orbifolds is trivial. The tetrahedral decomposition of the figure-eight knot complement in the 3-sphere is carried out in [T] pages 3.6 and 3.7. Finally, solving the holonomy equations in section 4.6 of [T] for $(p, q)=(5,1)$ produces a decomposition of $M_{(5,1)}$ into ideal hyperbolic tetrahedra (off of the surgered geodesic).

## II. Sphere-packing

We will be concerned with how densely equal radius balls can be packed without overlapping. In general, the density of $S$ with respect to (finite volume) $T$ is

$$
d(S, T)=\frac{\operatorname{vol}(S \cap T)}{\operatorname{vol}(T)}
$$

We can extend this notion to Euclidean $n$-space $\mathbf{E}^{n}$, i.e. $T=\mathbf{E}^{n}$ and $S=$ (the union of non-overlapping, equal-radius balls), by defining upper and lower densities

$$
d_{U}=\limsup _{r \rightarrow \infty} d(S, B(p, r)) \quad \text { and } \quad d_{L}=\liminf _{r \rightarrow \infty} d(S, B(p, r))
$$

where $B(p, r)$ is the radius $r$ ball in $\mathbf{E}^{n}$ centered at $p$. If $d_{L}=d_{U}$ then we have a notion of global density for $\mathbf{E}^{n}$. The fact that $d_{L}$ and $d_{U}$ are independent of the base point $p$ chosen is proven in [FT] pages 161,162 (see also pg. 261). The argument hinges on the fact that

$$
\lim _{r \rightarrow \infty} \frac{\operatorname{vol}(B(p, r+\varepsilon))}{\operatorname{vol}(B(p, r))}=1
$$

Attempting to use this notion of global density in hyperbolic $n$-space $H^{n}$ is problematic because

$$
\lim _{r \rightarrow \infty} \frac{\operatorname{vol}(B(p, r+\varepsilon))}{\operatorname{vol}(B(p, r))}=e^{\varepsilon(n-1)}
$$

(in $H^{3}$, vol $(B(p, r))=\pi(\sinh (2 r)-2 r)$ ). We will avoid this problem by dealing with a "local" notion of density. Given a collection $\mathscr{B}$ of equal radius, non-overlapping balls in $H^{n}$ we define the local density of a ball $B$ in $\mathscr{B}$ to be

$$
\ell d(B, \mathscr{B})=\frac{\operatorname{vol}(B \cap D)}{\operatorname{vol}(D)}=d(B, D)
$$

where $D=\left\{p \in H^{n}: p\right.$ is closer to $B$ than to any other ball $B^{\prime}$ in $\left.\mathscr{B}\right\}:=D(B, \mathscr{B})$ is the Dirichlet region for $B$ with respect to $\mathscr{B}$. This notion is ideally suited to studying volumes of hyperbolic 3-manifolds $M=H^{3} / \Gamma$ because, given an embedded ball in $M$, the collection of all lifts of this ball to $H^{3}$ gives a packing $\mathscr{B}$ of $H^{3}$ upon which $\Gamma$ acts transitively, and $D(B, \mathscr{B})$ for any $B$ in $\mathscr{B}$ is a fundamental domain for $M=H^{3} / \Gamma$ (see [G] Section 2.5). A similar notion holds for orbifolds $Q=H^{3} / \Gamma$, but we may have to "chop" $B$ and $D$ due to torsion elements in $\Gamma$. That is, if $\Gamma_{b}$ is the stabilizer of the center $b$ of $B$, then $D / \Gamma_{b}$ is a fundamental domain for $Q=H^{3} / \Gamma$ (see [Be] Section 9.6). This is not a problem, because $d(B, D)=d\left(B / \Gamma, D / \Gamma_{b}\right)$.

We can generalize local density to deal with a horoball packing ("horoball" is defined in Section III). The notion of a Dirichlet region $D=D(B, \mathscr{B})$ still makes sense if we define the distance of a point $p$ from a horoball $B$ to be the length of the unique perpendicular geodesic from $p$ to the horosphere boundary of $B$. The fact that $B \cap D$ and $D$ have infinite volume creates some problems. Thus, we define local density $\ell d(B, \mathscr{B})$ in a 2 -step procedure: Assume we are in upper-half-space $H^{3}$ and that $B$ is centered at the point at infinity. Then, we define

$$
d_{t}=\lim _{c \rightarrow \infty} \frac{\operatorname{vol}(B \cap D \cap A(t, c))}{\operatorname{vol}(D \cap A(t, c))}
$$

where $A(t, c)=\{(x, y, z):-c<x<c,-c<y<c$, and $z \geq t\}$. This definition is independent of the choice of origin (here the origin is $(0,0, t)$ ); the independence-of-origin proof is a re-working of the proof for $\mathbf{E}^{n}$ mentioned above, using the fact that horoballs have Euclidean structures on their horosphere boundaries and that $\operatorname{vol}(A(t, c))=c^{2} / 2 \cdot t^{2}$. Since $d_{t}$ is an increasing function of $t$, we can define $\ell d(B, \mathscr{B})=\lim _{t \rightarrow 0} d_{t}$.

This is the appropriate notion of local density to use in studying hyperbolic 3-manifolds $M=H^{3} / \Gamma$ with cusps. If we know that a cusped manifold contains an embedded cusp neighborhood, then lifting these cusp neighborhoods to $H^{3}$ gives a collection $\mathscr{B}$ of disjoint horoballs $B$ upon which $\Gamma$ acts transitively; but $D(B, \mathscr{B})$ is no longer a fundamental domain for $\Gamma$. To get a fundamental domain $F$ for $\Gamma$
we simply take $F$ to be a fundamental domain for the action of $\Gamma_{c}$ on $D(B, \mathscr{B})$ where $\Gamma_{c}$ is the stabilizer of the center $c$ of $B$ ( $\Gamma_{c}$ is made up entirely of parabolic transformations). Using the above definition of local density for horoball packings, we have

$$
\ell d(B, \mathscr{B})=\frac{\operatorname{vol}(B \cap F)}{\operatorname{vol}(F)} .
$$

The above holds verbatim for cusped orbifolds $Q=H^{3} / \Gamma$ except that $\Gamma_{c}$ may have elliptic as well as parabolic transformations.

We now state Böröczky's theorem (which applies to constant curvature spaces of arbitrary dimension) in the case of hyperbolic 3-space (See [B] theorems 1 and 4):

THEOREM (Böröczky). Consider 4 spheres of radius $r$ in $H^{3}$ each touching all the others. Their centers determine a regular tetrahedron $T$ of edge length $2 r$ and dihedral angles $2 \alpha$ where $\sec (2 \alpha)=2+\operatorname{sech}(2 r)$. Let $S$ be the union of the 4 balls of radius $r$ bounded by the 4 spheres. Then, for any radius $r$ sphere-packing $\mathscr{B}$ in $H^{3}$ the local density satisfies

$$
\ell d(B, \mathscr{B}) \leq \frac{\operatorname{vol}(S \cap T)}{\operatorname{vol}(T)}=\frac{(6 \alpha-\pi)(\sinh (2 r)-2 r)}{\operatorname{vol}(T)}:=d(r) .
$$

This result holds for horosphere packings as well, in which case the centers of the horoballs (points of tangency with $\partial H^{3}$ ) determine an ideal regular tetrahedron $T$, and

$$
\ell d(B, \mathscr{B}) \leq \frac{\operatorname{vol}(S \cap T)}{\operatorname{vol}(T)}=\frac{4(\sqrt{3} / 8)}{V}=\frac{\sqrt{3}}{2 V} \approx 0.853 \text {, where } \quad V=\operatorname{vol}(T) \text {. }
$$

Remark. It was shown in $[\mathrm{BF}]$ that $d(r)$ is an increasing function of $r$. The number $d(0) \approx 0.7797$ is the density (with respect to the regular tetrahedron they determine) of 4 mutually touching equal radius balls in $\mathbf{E}^{3}$. The 4 horoball packing can be extended uniformly to all of $H^{3}$. In some sense, this is the densest packing of equal radius spheres in $H^{3}$. The densest packing of equal radius spheres in $\mathbf{E}^{3}$ is not known even though the analog of the above theorem holds for $\mathbf{E}^{n}$. The difficulty is that the above tetrahedral packing does not extend uniformly to a global packing of $\mathbf{E}^{3}$ (See [SL] and [R]).

## III. Remarks on hyperbolic space

As mentioned in Section 1, we are working in the upper-half-space model for hyperbolic 3 -space, $H^{3}=\{(x, y, z): z>0\}$ with metric $d s^{2}=\left(d x^{2}+d y^{2}+d z^{2}\right) / z^{2}$ and volume form $d V=d x d y d z / z^{3} ; \partial H^{3}=\mathbf{C} \cup\{\infty\}$. The orientation-preserving isometries of hyperbolic 3-space can be identified either with $P G L_{2}(\mathbf{C})=G L_{2}(\mathbf{C}) /$ $\mathbf{C}^{*}$ or $P S L_{2}(\mathbf{C})=S L_{2}(\mathbf{C}) / \pm I$ (See [S] pg. 448-449). But note that if $\mathscr{O}_{d}$ is the ring of integers in $\mathbf{Q}(\sqrt{-d})$ then $P G L_{2}\left(\mathcal{O}_{d}\right) / P S L_{2}\left(\mathcal{O}_{d}\right)=\mathbf{Z} / 2 \mathbf{Z}$ where $P G L_{2}\left(\mathcal{O}_{d}\right)=$ $G L_{2}\left(\mathcal{O}_{d}\right) /\left\{\lambda I: \lambda \in \mathcal{O}_{d}^{*}\right\}$ and $P S L_{2}\left(\mathcal{O}_{d}\right)=S L_{2}\left(\mathcal{O}_{d} / \pm I\right.$ (See $[\mathrm{H}] \mathrm{pg}$. 346). Thus, the use of $P G L_{2}\left(\mathcal{O}_{d}\right)$, and not $P S L_{2}\left(\mathcal{O}_{d}\right)$, in the statement of Theorem 1.

In $H^{3}$ a horoball $B$ is either:

1) a Euclidean ball in $\{(x, y, z): z \geq 0\}$ which is tangent to the $x y$ plane, the point of tangency being the center of $B$; or it is
2) a half space of the form $\{(x, y, z): z \geq a>0\}$, in which case the center of $B$ is the point at $\infty$.

Note that the hyperbolic metric on $H^{3}$ induces the Euclidean metric $d s^{2}=\left(d x^{2}+d y^{2}\right) / a^{2}$ on $\partial B \cap H^{3}=\{(x, y, z): z=a\}$, that is the bounding horosphere of the horoball $B$ is flat. There is no real distinction between horoballs of type 1 and type 2 , because there are isometries of $H^{3}$ taking either to the other. In particular, all horospheres are flat.

A discrete group $\Gamma$ is said to have a cusp if $\Gamma$ contains a parabolic element $\gamma$. Let the fixed point of $\gamma$ be $p \in \partial H^{3}$; then $\Gamma_{p}$, the stabilizer of $p$, is of importance. $\Gamma_{p}$ contains no hyperbolic elements (See [Be] theorem 5.1.2). In the manifold case $\Gamma_{p}$ contains only parabolic transformations. In the orbifold case $\Gamma_{p}$ may have elliptic elements.

## IV. Sphere-packing and volume

It can be proved that short geodesics (length less than approximately 0.107 ) in complete hyperbolic 3-manifolds have embedded tubular neighborhoods ("solid tubes"), and that the shorter the geodesic the bigger the volume of the solid tube (See [M1]). This solid tube construction can be used to produce a lower bound for the volume of complete hyperbolic 3-manifolds (without cusps). The argument is as follows. A non-cusped hyperbolic 3-manifold $M=H^{3} / \Gamma$ must have either an embedded ball of radius $r$ or a geodesic of length less than $2 r$. If we take $r=0.053475$ then the embedded ball $B(0.053475)$ contributes at least 0.00064 to the volume of $M$, while a geodesic of length at most $2 r=0.10695$ has an embedded tubular neighborhood of volume at least 0.00068 (See [M1]). Thus, the volume of a closed hyperbolic 3 -manifold must be greater than 0.00064 . By
choosing a smaller $r$ we get more volume in the solid-tube case, but less in the embedded-ball case; thus the overall volume estimate is lower. The value $r=0.053475$ was chosen to maximize the overall volume estimate; call this value or $r$ the "trade-off value". (Since cusped hyperbolic 3-manifolds have volume greater than $\sqrt{3} / 4$ we have that all complete hyperbolic 3-manifolds have volume at least 0.00064 , i.e. $V_{1}>0.00064$ (See [M1]).)

Böröczky's theorem can be used to improve the lower bound of 0.00064 . Specifically, Böröczky's theorem yields an improved volume contribution in the embedded-ball case. The argument is as follows. As mentioned in Section 2, the lifts of an embedded ball $B(r)$ to $H^{3}$ yield a packing $\mathscr{B}$ of $H^{3}$; and a Dirichlet domain $D(B, \mathscr{B})$ for any ball $B$ in the packing is a fundamental domain for $\Gamma$. Using Böröczky's theorem, we have $\operatorname{vol}(B(0.053475)) / \operatorname{vol}\left(H^{3} / \Gamma\right)=\operatorname{vol}$ $(B(0.053475)) / \operatorname{vol}(D(B, \mathscr{B})) \leq d(0.053475)$. Thus vol $\left(H^{3} / \Gamma\right) \geq \operatorname{vol}(B(0.053475)) /$ $d(0.053475)>0.00082$, and we have improved our estimate if an embedded ball of radius 0.053475 sits in $M$. This technique does not effect the solid-tube contribution; thus, if $r$ is taken as 0.053475 then our lower bound is still 0.00064 . However, we can take a smaller value of $r$ and improve our solid-tube volume contribution while only marginally effecting our embedded-ball volume. In particular taking $r=0.053463$ yields a solid-tube volume greater than 0.00082 while the embedded-ball volume is still greater than 0.00082 . Thus, we have that 0.00082 is a lower bound for the volume of complete hyperbolic 3-manifolds; that is $V_{1}>0.00082$.

For orbifolds $Q=H^{3} / \Gamma$ without cusps the analysis is essentially the same except that the relevant "trade-off" radius is 0.0535 and the volume of the "chopped" solid ball is roughly 0.00000134 (see [M2]). Thus by the density argument $\operatorname{vol}(Q)>0.0000017$, i.e. $V_{1}^{\prime}>0.0000017$.

In dealing with cusped manifolds $M=H^{3} / \Gamma$ we do not have to resort to this trading-off argument. In [M1] it is shown that there is a cusp neighborhood $C$ in $M$ of volume at least $\sqrt{3} / 4$. This neighborhood yields a horoball packing $\mathscr{B}$ of $H^{3}$. Further, given $B$ in $\mathscr{B}$ centered at $p$ we have that a fundamental domain $F$ for the action of $\Gamma_{p}$ on $D(B, \mathscr{B})$ is a fundamental domain for $\Gamma$. Applying Böröczky's theorem, we have

$$
\frac{\operatorname{vol}(C)}{\operatorname{vol}(M)}=\frac{\operatorname{vol}(B \cap F)}{\operatorname{vol}(F)}=d(B, \mathscr{B}) \leq \sqrt{3} / 2 V .
$$

Thus, $\quad \operatorname{vol}(M) \geq \operatorname{vol}(C) /(\sqrt{3} / 2 V) \geq(\sqrt{3} / 4)(2 V / \sqrt{3})=V / 2 \quad$ and $\quad V_{\omega} \geq V / 2 \approx$ 0.5072 .

This argument works for cusped orbifolds $Q=H^{3} / \Gamma$ as well, except that the cusp neighborhood $C$ in $Q$ in the worst case only contributes $\sqrt{3} / 24$ to the volume
of $Q$ (See [M2]). Thus $\operatorname{vol}(Q) \geq(\sqrt{3} / 24)(2 V / \sqrt{3})=V / 12, V_{c}^{\prime} \geq V / 12 \approx 0.0846$. Since $Q_{1}=H^{3} / P G L_{2}\left(O_{3}\right)$ has volume $V / 12$ we have (See Section 1):

THEOREM. $Q_{1}=H^{3} / P G L_{2}\left(\mathcal{O}_{3}\right)$ has minimum volume among all orientable cusped hyperbolic 3-orbifolds.

Remark. There are cusped orbifolds on which Dehn surgery cannot be performed. Consequently, unlike the manifold case, there are cusped hyperbolic 3 -orbifolds whose volumes are isolated- $Q_{1}$ is such an orbifold. The question of finding "the least limiting orbifold" remains open.

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## Mathematics Department

Boston University
111 Cummington Street
Boston, MA02215, USA
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[^1]:    ${ }^{2}$ Jeff Weeks has found a hyperbolic 3-manifold with less volume than $M_{(5,1)}$ (Princeton Univ. Ph.D. thesis, 1985).
    ${ }^{3}$ Colin Adams has improved the left-hand inequality for $V_{\omega}$ by a factor of 2 (preprint, 1985).

