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Ping Pong on CAT(0) cube complexes

Aditi Kar and Michah Sageev

Abstract. Let G be a group acting properly and essentially on an irreducible, non-Euclidean finite dimensional CAT(0) cube complex X without a global fixed point at infinity. We show that for any finite collection of simultaneously inessential subgroups $\{H_1, \dots, H_k\}$ in G , there exists an element g of infinite order such that $\forall i, \langle H_i, g \rangle \cong H_i * \langle g \rangle$. We apply this to show that any group, acting faithfully and geometrically on a non-Euclidean possibly reducible CAT(0) cube complex, has property P_{naive} i.e. given any finite list $\{g_1, \dots, g_k\}$ of elements from G , there exists g of infinite order such that $\forall i, \langle g_i, g \rangle \cong \langle g_i \rangle * \langle g \rangle$. This applies in particular to the Burger–Mozes simple groups that arise as lattices in products of trees. The arguments utilize the action of the group on the boundary of *strongly separated ultrafilters* and moreover, allow us to summarize equivalent conditions for the reduced C^* -algebra of the group to be simple.

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1. Introduction

Felix Klein’s Ping Pong Lemma is a widely used criterion for determining if a collection of group elements generate a non-abelian free subgroup and more generally, for constructing subgroups which are non-trivial free products. In this paper, we employ the ping pong lemma in the setting of groups acting on CAT(0) cube complexes to construct subgroups which split as non-trivial free products, as described below in the Main Theorem.

An action of a group G on a CAT(0) cube complex X is said to be *essential* if for any given orbit of G , there are orbit points which are arbitrarily deep inside any half space of X . A collection of groups G_1, \dots, G_k acting on X are said to be *simultaneously inessential* if there is a half space \mathfrak{h} and a vertex $v \in X$ such that $\cup_i G_i(v) \subset \mathfrak{h}$. A large class of examples of simultaneously inessential subgroups arise when G is Gromov hyperbolic and acts properly cocompactly on X and the G_i ’s are a finite collection of infinite index quasi-convex subgroups of G (see Proposition 2.1). Our goal is the following.

Main Theorem. *Let X be a finite dimensional, irreducible, non-Euclidean CAT(0) cube complex and let G be a group acting essentially and properly on X , without a global fixed point at infinity. Assume further that G has no finite normal subgroup. Let A_1, \dots, A_n be a collection of simultaneously inessential subgroups of G . Then there exists $g \in G$ of infinite order, such that for each i , $\langle g, A_i \rangle \cong \langle g \rangle * A_i$.*

If H is a quasi-convex subgroup in a non-elementary hyperbolic group G , then Theorem 1 holds and there exists $g \in G$ such that the subgroup generated by g and H is the free product $\langle g \rangle * H$; this was proved by Arzhantseva in [1].

The key step in the proof of the Main Theorem that allows us to play ping pong is Proposition 3.4 which says that for any collection A_1, \dots, A_n of simultaneously inessential subgroups, one can find a half space \mathfrak{h} in X such that $a\mathfrak{h}$ is contained in the complement of \mathfrak{h} , for all nontrivial $a \in \cup_i A_i$.

In the process of proving the Proposition, we construct a new ultrafilter boundary $S(X)$ built out of *strongly separated* ultrafilters of X . The strongly separated ultrafilters have nice properties. For example, the median of three strongly separated ultrafilters is a vertex of X . We use this to show that the fixed set of every non-trivial element of the group has empty interior on the boundary. We summarize this into the proposition below, which is proved at the end of Section 3.

Proposition 1.1. *Let X be a non-Euclidean irreducible CAT(0) cube complex X . Suppose a group G is acting essentially on X without a global fixed point at infinity. Then, the compact G -space $S(X)$ is minimal and strongly proximal and hence, a G -boundary. Moreover, if the action of G on X is proper and G has no non-trivial finite normal subgroups, then the action of G on $S(X)$ is topologically free.*

When X splits into irreducible direct factors $X_1 \times \dots \times X_n$ and each factor X_i is non-Euclidean then $S(X)$ decomposes as a direct product of the $S(X_i)$ and Proposition 1.1 naturally extends to the reducible case. A similar ultrafilter boundary was studied by Fernos in [8].

An application of the Main Theorem: property P_{naive} . We use the Main Theorem to study property P_{naive} for groups acting on CAT(0) cube complexes.

Property P_{naive} was introduced by Bekka, de la Harpe and Cowling [3] to study the ideal structure of group C^* -algebras. We give a brief introduction to P_{naive} in Section 4.

Definition 1.2. A group G has property P_{naive} if for every finite subset $F \subset G$ there exists an element $y \in G$ of infinite order such that given $g \in F$, the subgroup $\langle g, y \rangle$ is canonically isomorphic to the free product $\langle g \rangle * \langle y \rangle$.

Corollary 1.3. *Suppose a group G is acting properly and cocompactly on a finite dimensional non-Euclidean CAT(0) cube complex. If G has no non-trivial finite normal subgroups then G has property P_{naive} .*

In the irreducible case, property P_{naive} is a direct consequence of the Main Theorem, as given by Corollary 3.2. When the underlying CAT(0) cube complex is reducible, we prove property P_{naive} for lattices in $\text{Aut}(X)$, where X is locally finite, co-compact and has no Euclidean factor (see Theorem 4.1). Examples of groups satisfying the hypotheses of Theorem 4.1, which were not known up to now to satisfy P_{naive} , are the Burger–Mozes simple groups [5], which arise as lattices in products of trees.

The study of property P_{naive} was initiated by Bekka, Cowling and de la Harpe as a means to establish C^* -simplicity of group C^* -algebras. Here, we use property P_{naive} from the above Corollary and several previously known results to provide necessary and sufficient conditions for the reduced C^* -algebra of a CAT(0) cube complex group to be simple. This last property is commonly referred to as C^* -simplicity.

Corollary 1.4. *The following are equivalent for a group G acting properly and co-compactly on a finite dimensional CAT(0) cube complex X .*

- (1) G has property P_{naive} .
- (2) G is C^* -simple.
- (3) Every non-trivial conjugacy class of G is infinite.
- (4) The amenable radical of G is trivial.
- (5) The G -action is faithful and X is non-Euclidean.

Recent research has yielded more sophisticated techniques for establishing C^* -simplicity. Kalantar and Kennedy [11] have brought in dynamical techniques showing that a group G is C^* -simple if and only if there exists a G -boundary on which the G -action is topologically free. Using Proposition 1.1, we get an application of their Theorem to groups acting properly (not necessarily, co-compactly) on CAT(0) cube complexes (refer to Proposition 1.1) without a global fixed point at infinity.

Kalantar and Kennedy's methods were developed further by Breuillard, Kalantar, Kennedy and Ozawa [4]. Recall [4, Theorem 3.1] which says that if a discrete group G has countably many amenable subgroups, then G is C^* -simple if and only if the amenable radical is trivial. In [15], Sageev and Wise showed that groups acting on finite dimensional CAT(0) cube complexes satisfy the Tits Alternative so long as one knows the action is proper and there is a bound on the size of the finite subgroups. Their proof works equally well if the existence of a bound on the size of finite subgroups is replaced by the weaker condition that, every locally finite subgroup is finite. Therefore, if G is acting properly on a finite dimensional CAT(0) cube complex and every locally finite subgroup of G is finite, then the Tits Alternative for G implies that every amenable subgroup is finitely generated virtually abelian. Consequently, if G is countable, then G can have only countably many amenable subgroups. We get the following interesting application of [4, Theorem 3.1].

Proposition 1.5. *Let G be a countable discrete group such that every locally finite subgroup is finite. Suppose G acts properly on a finite dimensional CAT(0) cube complex. Then, G is C^* -simple if and only if its amenable radical is trivial.*

This generalizes Le Boudec's Proposition 3.2 from [10], which deals with the case when X is a product of trees. When the locally finite subgroups are not necessarily finite, groups acting properly on finite dimensional CAT(0) cube complexes can have uncountably many amenable subgroups. For instance, one can make a direct sum of infinitely many copies of a finite cyclic group act properly on a tree.

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2. Preliminaries

In this section, we collect some relevant notions and results on CAT(0) cube complexes, as well as introducing a few new notions. We refer the reader to [6, 12] and [14] for details on the relevant background material. In particular, we will assume familiarity with hyperplanes and halfspaces. We will always assume that X is a finite dimensional CAT(0) cube complex. We will use \mathfrak{h} (and other gothic letters) to refer to a halfspace, \mathfrak{h}^* to refer to the complementary halfspace and $\hat{\mathfrak{h}}$ to refer to a hyperplane.

2.1. Essentiality. A CAT(0) cube complex is called *essential* if every halfspace \mathfrak{h} contains arbitrarily large metric balls. This is the same as saying that every halfspace contains arbitrarily deep points: points arbitrarily far away from its bounding hyperplane.

If $\text{Aut}(X)$ acts on X without a global fixed point either in X or at infinity (the visual boundary), then X contains an $\text{Aut}(X)$ invariant essential core. Thus, it is reasonable to discuss only essential CAT(0) cube complexes, and we shall assume this from now on.

An action of a group G on X is said to be an *essential action* if for any given orbit, there are orbit points arbitrarily deep inside every halfspace. When X is essential and the action is inessential there exists a halfspace \mathfrak{h} and a vertex v such that $G(v) \subset \mathfrak{h}$. A collection of subgroups $G_1, \dots, G_n < \text{Aut}(X)$ are said to be *simultaneously inessential* if there exists halfspace \mathfrak{h} and a vertex v in X such that $\cup_i G_i(v) \subset \mathfrak{h}$.

A large class of examples of simultaneously inessential subgroups arises in the context of hyperbolic groups.

Proposition 2.1. *Let G be a hyperbolic group which acts properly, cocompactly and essentially on a CAT(0) cube complex X . Let G_1, \dots, G_n be a finite collection*

of infinite index quasiconvex subgroups. Then G_1, \dots, G_n are simultaneously inessential.

We delay the proof of Proposition 2.1 until Section 3.

2.2. Products. We say that X is reducible if it admits a decomposition as a product of two non-trivial CAT(0) cube complexes. A finite dimensional CAT(0) cube complex always admits a canonical decomposition as a product of irreducible complexes.

If X is essential then each irreducible factor of X is also essential. Those irreducible factors that are not quasi-isometric to a real line are called *non-Euclidean* factors. More explicitly, an irreducible, essential CAT(0) cube complex is called non-Euclidean if it is not quasi-isometric to a real line. A (possibly reducible) essential CAT(0) cube complex is called non-Euclidean if all of its factors are non-Euclidean. Essential, irreducible, non-Euclidean complexes will be the subject of Section 3.

2.3. Facing triples and strongly separated hyperplanes. The notion of a non-Euclidean CAT(0) cube complex can be characterized in terms of facing triples of hyperplanes. By a facing triple of hyperplanes we mean a pairwise disjoint triple of hyperplanes that bound halfspaces which are also pairwise disjoint. Equivalently, no hyperplane of the triple separates the other two from one another. We then have the following lemma.

Lemma 2.2 (Facing Triples). *Let X be an essential, non-Euclidean CAT(0) cube complex such that $\text{Aut}(X)$ acts with no global fixed point at infinity. Then for every halfspace \mathfrak{h} , there exists a facing triple $\hat{\mathfrak{h}}, \hat{\mathfrak{k}}, \hat{\mathfrak{m}}$ with $\hat{\mathfrak{k}}, \hat{\mathfrak{m}} \subset \mathfrak{h}$.*

An important lemma for us regarding irreducible cube complexes involves strongly separated pairs. A pair of disjoint hyperplanes $\hat{\mathfrak{h}}$ and $\hat{\mathfrak{k}}$ are called *strongly separated* if there are no hyperplanes that intersect both $\hat{\mathfrak{h}}$ and $\hat{\mathfrak{k}}$. We will also refer to the corresponding nested pair of halfspaces $\mathfrak{h} \subset \mathfrak{k}$ as being strongly separated. We then have the following lemma.

Lemma 2.3 (Strongly Separated Pairs). *Let X be an essential non-Euclidean CAT(0) cube complex such that $\text{Aut}(X)$ acts without a global fixed point at infinity. Then for every halfspace \mathfrak{h} there exists a halfspace $\mathfrak{k} \subset \mathfrak{h}$ such that $\hat{\mathfrak{h}}$ and $\hat{\mathfrak{k}}$ are strongly separated.*

2.4. Skewering. A halfspace \mathfrak{h} is said to be *skewered* by an automorphism $g \in \text{Aut}(X)$ if $g\mathfrak{h} \subset \mathfrak{h}$. We say that g skewers the hyperplane $\hat{\mathfrak{h}}$ if g skewers \mathfrak{h} or \mathfrak{h}^* . The relevant lemma for us regarding skewering is the following.

Lemma 2.4 (Double Skewering). *Let X be essential and G act on X either cocompactly or without a global fixed point at infinity. Then for every pair of halfspaces $\mathfrak{h} \subset \mathfrak{k}$, there exists $g \in G$ such that $g\mathfrak{k} \subset \mathfrak{h}$.*

As a corollary of the Double Skewering Lemma, we have that every halfspace is skewered by some element. For given a halfspace \mathfrak{h} , there exists some $\mathfrak{k} \subset \mathfrak{h}$ and then the element ensured by the Double Skewering Lemma skewers \mathfrak{h} .

In fact, a generalization of this for products can be established. More precisely (Theorem C of [6]), one can show the following.

Theorem 2.5. *Let $X = X_1 \times \cdots \times X_n$ be a product of infinite, locally compact CAT(0) cube complexes such that $\text{Aut}(X_i)$ acts cocompactly on X_i for each i . Suppose that G is a lattice in $\text{Aut}(X)$. Suppose that $\mathfrak{h}_i \subset \mathfrak{k}_i$ are nested halfspaces in each factor X_i . Then there exists $g \in G$ which simultaneously double skewers these hyperplanes. That is to say, for each i , $g\mathfrak{k}_i \subset \mathfrak{h}_i$.*

2.5. The Roller Boundary. As before, let X be essential. We will consider here a certain part of the Roller boundary which will be useful to us (see [14] for basics on ultrafilters and the Roller boundary). Let \mathcal{H} denote the collection of halfspaces of X . Recall that an ultrafilter on \mathcal{H} is a subset $\alpha \subset \mathcal{H}$ satisfying

- (1) (Choice) For each pair $\mathfrak{h}, \mathfrak{h}^*$, exactly one of \mathfrak{h} or \mathfrak{h}^* is in α .
- (2) (Consistency) If $\mathfrak{h} \subset \mathfrak{k}$ and $\mathfrak{h} \in \alpha$ then $\mathfrak{k} \in \alpha$.

The collection of all ultrafilters $\mathcal{U}(X)$ has a natural topology induced by the Tychonoff topology on $2^{\mathcal{H}}$. This has as a basis the collection of *halfspace neighborhoods*, where a halfspace neighborhood is a subset of $\mathcal{U}(X)$ of the form

$$U_{\mathfrak{h}} \equiv \{\alpha \in \mathcal{U}(X) \mid \mathfrak{h} \in \alpha\}$$

One can show that the collection of ultrafilters is then closed in $2^{\mathcal{H}}$. The vertices of X correspond to those ultrafilters satisfying the descending chain condition (DCC). The Roller Boundary is defined to be the complement in $\mathcal{U}(X)$ of the DCC ultrafilters. It is closed in $\mathcal{U}(X)$ as well and is therefore compact.

On the opposite side of the spectrum for ultrafilters, we have what we call *strongly separated* ultrafilters.

Definition 2.6. An ultrafilter α is *strongly separated* if there exists an infinite nested sequence of halfspaces $\mathfrak{h}_1 \supset \mathfrak{h}_2 \cdots \in \alpha$ such that \mathfrak{h}_i and \mathfrak{h}_{i+1} are strongly separated. We call such a sequence of halfspaces a *strongly separated sequence* of halfspaces.

It is easy to see that there are strongly separated sequences of halfspaces, since by Lemma 2.3, any halfspace \mathfrak{h} contains a halfspace strongly separated from it. In fact, by employing the Facing Triple Lemma, there exist uncountably many strongly separated sequences. A key observation is that a strongly separated sequence uniquely determines an ultrafilter.

Lemma 2.7. *For every strongly separated sequence of halfspaces $\mathfrak{h}_1 \supset \mathfrak{h}_2 \cdots$, there exists a unique ultrafilter α such that $\mathfrak{h}_i \in \alpha$.*

Proof. We define an ultrafilter as follows.

$$\alpha = \{h \mid h_i \subset h \text{ for infinitely many } i\}$$

By definition $h_i \in \alpha$ for each i . We are left to check that α satisfies the two conditions necessary for an ultrafilter (choice and consistency) and then that it is unique. Any given hyperplane \hat{h} may intersect at most one of the \hat{h}_i 's. It follows that exactly one of the halfspaces h, h^* contains infinitely many h_i 's, thus precisely one of h, h^* is in α . The consistency condition is immediate since if infinitely many h_i satisfy $h_i \subset h$ and $h \subset k$ then $h_i \subset k$ for infinitely many i .

To see uniqueness, let β be an ultrafilter such that $h_i \in \beta$ for all i . Then for any $h \in \beta$, observe that \hat{h} may intersect at most one \hat{h}_i . Consequently, either h contains infinitely many h_i 's or h^* contains infinitely many h_i 's. Choose one such h_i . Since $h, h_i \in \beta$, by the consistency condition we have that $h_i \subset h$ (and not $h_i \subset h^*$). This means that $h \in \alpha$. So α and β make the same choices for each pair h, h^* and hence $\alpha = \beta$. □

We define $S(X)$ to be the closure in \mathcal{U} of the collection of strongly separated ultrafilters. It is a compact subspace of the Roller Boundary.

Next we see that strongly separated ultrafilters behave nicely with respect to medians. Recall that given three ultrafilters α, β, γ , the *median* of α, β and γ is defined as

$$\text{med}(\alpha, \beta, \gamma) \equiv (\alpha \cap \beta) \cup (\beta \cap \gamma) \cup (\gamma \cap \alpha).$$

Lemma 2.8. *Let α, β, γ be distinct strongly separated ultrafilters. Then the $\text{med}(\alpha, \beta, \gamma)$ satisfies DCC and hence is a vertex of X .*

Proof. We need to show that $\mu = \text{med}(\alpha, \beta, \gamma)$ satisfies the descending chain condition (see Figure 1). Suppose that $h_1 \supset h_2 \cdots$ is an infinite sequence of halfspaces such that $h_i \in \mu$. Then after passing to a subsequence, we may assume that $h_i \in \alpha \cap \beta$ for all i . Since α and β are distinct strongly separated ultrafilters, there exist $h \in \alpha$ and $k \in \beta$ such that $h \cap k = \emptyset$ and \hat{h} and \hat{k} are strongly separated. Since $h_i \in \alpha$, we have that $h_i \cap h \neq \emptyset$ and $h_i \cap k \neq \emptyset$. But if $\{h_i\}$ is an infinite descending sequence of hyperplanes, we must have that for i sufficiently large, $h_i \subset h$ or $\hat{h}_i \cap \hat{h} \neq \emptyset$. Similarly, for i sufficiently large, we must have $h_i \subset k$ or $\hat{h}_i \cap \hat{k} \neq \emptyset$. But this contradicts the fact that \hat{h} and \hat{k} are strongly separated. □

We will also need the following lemma telling us that halfspace neighborhoods form a basic collection of open neighborhoods for the strongly separated ultrafilters.

Lemma 2.9. *Let $U \subset S(X)$ be an open neighborhood of $\alpha \in S(X)$, where α is a strongly separated ultrafilter. Then there exists a halfspace h such that $\alpha \in (U_h \cap S(X)) \subset U$.*

Proof. Since the halfspace neighborhoods U_h serve as a collection of sub-basic open sets for the topology on $\mathcal{U}(X)$ and hence of $S(X)$, it suffices to prove this when U is a finite intersection of halfspace neighborhoods of α . That is, we assume that there exist halfspaces h_1, \dots, h_n such that $U = \cap U_{h_i} \cap S(X)$. Since α is a strongly separated ultrafilter, there exists a strongly separated sequence $\mathfrak{k}_1 \supset \mathfrak{k}_2 \cdots$ with $\mathfrak{k}_i \in \alpha$. For each h_i , we then know that there exists a tail of the strongly separated sequence contained in h_i . Consequently, there exists a single \mathfrak{k}_j such that $\mathfrak{k}_j \subset h_i$ for all i . We then have that $\alpha \in U_{\mathfrak{k}_j} \cap S(X) \subset U$ as required. \square

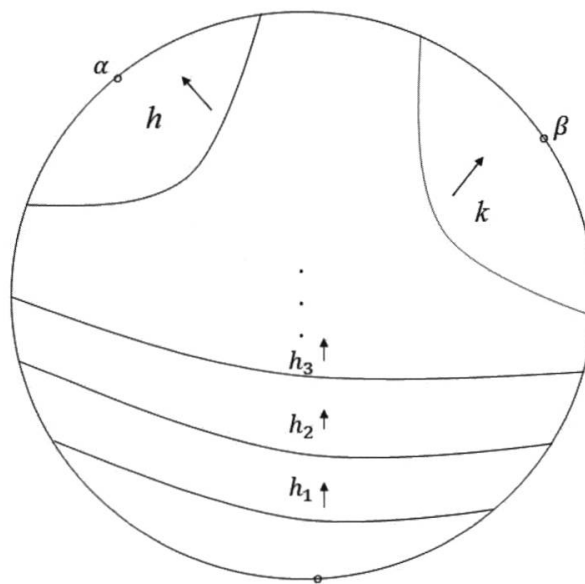


Figure 1. The median of strongly separated ultrafilters satisfies DCC.

2.6. Ping Pong. We will use the following version of the Ping Pong Lemma.

Lemma 2.10 (Ping-Pong Lemma). *Let S be a set and let G be a group acting on S . Let $H, K < G$ be subgroups of G . Suppose that there exist two disjoint subsets $U, V \subset S$ such that for all for all $1 \neq h \in H$, we have $hU \subset V$ and for all $1 \neq k \in K$, $kV \subset U$. Then $\langle H, K \rangle \cong H * K$.*

3. Irreducible complexes

In all that follows, we will assume that X is a finite dimensional, irreducible, essential, non-Euclidean CAT(0) cube complex, and that G is a group acting on X essentially, properly, and without global a fixed point at infinity. We also assume that G has no finite normal subgroup.

Theorem 3.1 (Main Theorem). *Let A_1, \dots, A_n be a collection of simultaneously inessential subgroups of G . Then there exists $g \in G$ of infinite order, such that for each i ,*

$$\langle g, A_i \rangle \cong \langle g \rangle * A_i .$$

Corollary 3.2. *Suppose that a group G is acting on a finite-dimensional irreducible non-Euclidean CAT(0) cube complex X . If the action of G on X is essential, proper and has no global fixed point at infinity, and, G has no non-trivial finite normal subgroups then G has property P_{naive} .*

First of all, we will need the following lemma.

Lemma 3.3. *Suppose that $a \in G$ is nontrivial. Then $\text{Fix}(a) \subset S(X)$ has empty interior.*

Proof. Suppose that a is non-trivial and fixes an open subset $U \subset S(X)$. By Lemma 2.9, there exists a half space \mathfrak{h} such that the halfspace neighborhood $U_{\mathfrak{h}} \subset S(X)$. Consider three strongly separated ultrafilters in $U_{\mathfrak{h}}$ and let v denote their median. By Lemma 2.8, the ultrafilter v is a vertex in X . Since the action is essential, there exists $g \in G$ such that g skewers \mathfrak{h} , so that $g\mathfrak{h} \subset \mathfrak{h}$. By the Lemmas 2.3 and 2.4, we may further assume that $g\hat{\mathfrak{h}}$ and $\hat{\mathfrak{h}}$ are strongly separated.

We now consider the elements $a_n \equiv g^{-n}ag^n$. Let $\mathfrak{h}_n = g^{-n}\mathfrak{h}$. Note that by our choice of g above, the sequence $\{\mathfrak{h}_n^*\}$ is a strongly separated sequence of halfspaces.

Note that a_n fixes $U_n \equiv U_{\mathfrak{h}_n}$. Since $v \in \mathfrak{h} \subset g^{-n}\mathfrak{h}$ it follows that v is the median of three points contained in U_n , and therefore $a_nv = v$. By the properness of the action, there are only finitely many possibilities for a_n , so that we may pass to a subsequence of $\{a_n\}$ such that $a_n = b$ for all n . We then have

$$\bigcup_n U_n \subset \text{Fix}(b) = \{y \in S(X) | by = y\}.$$

Because the action is proper, the kernel of the action on $S(X)$ is a finite normal subgroup and because G has no finite normal subgroup, we have $\text{Fix}(b) \neq S(X)$. But now $\text{Fix}(b)$ is closed. So there exists a halfspace \mathfrak{k} such that $U_{\mathfrak{k}} \subset S(X) - \text{Fix}(b)$. Consequently, we have that $\hat{\mathfrak{k}} \cap \mathfrak{h}_n^*$, for all n . But this is a contradiction, since $\{\mathfrak{h}_n^*\}$ is a strongly separated sequence of halfspaces. □

The key to proving the main theorem is the following proposition, which will allow us to play ping-pong.

Proposition 3.4. *Let A_1, \dots, A_n be a collection of simultaneously inessential subgroups of G . Then there exists a halfspace \mathfrak{k} in X , such that $a\mathfrak{k} \subset \mathfrak{k}^*$ for all non-trivial $a \in \bigcup_i A_i$.*

Proof. To avoid writing indices, we will first give the proof for the case of a single subgroup A and then later explain how this is done for finitely many subgroups.

We will construct a combinatorial convex hull for $A(v)$, where v is some vertex of X . For a halfspace \mathfrak{h} , let $C(\mathfrak{h})$ denote the carrier of \mathfrak{h} , namely the union of cubes that intersect \mathfrak{h} non-trivially. It is easy to see that $C(\mathfrak{h})$ is a convex subcomplex of X (see [9]). Now, given a halfspace \mathfrak{h} such that $A(v) \subset \mathfrak{h}$, we define

$$C_{\mathfrak{h}} = \bigcap_{a \in A} C(a\mathfrak{h}).$$

The inessentiality assumption tells us that there exists such an \mathfrak{h} , and since $C_{\mathfrak{h}}$ is the intersection of convex subcomplexes, it is convex. Also, $C_{\mathfrak{h}}$ is invariant under A .

Remark. It is convex in both the usual CAT(0) sense but also in the ℓ_1 sense: every combinatorial edge-geodesic between vertices in $C_{\mathfrak{h}}$ remains in $C_{\mathfrak{h}}$.

Choose some halfspace $\mathfrak{k}_1 \subset \mathfrak{h}^*$ such that $\hat{\mathfrak{h}}$ and $\hat{\mathfrak{k}}_1$ are strongly separated.

We observe that every hyperplane which intersects $C_{\mathfrak{h}}$ does not intersect $\hat{\mathfrak{k}}_1$, since $C_{\mathfrak{h}} \subset \mathfrak{h}$ and $\hat{\mathfrak{h}}$ and $\hat{\mathfrak{k}}_1$ are strongly separated.

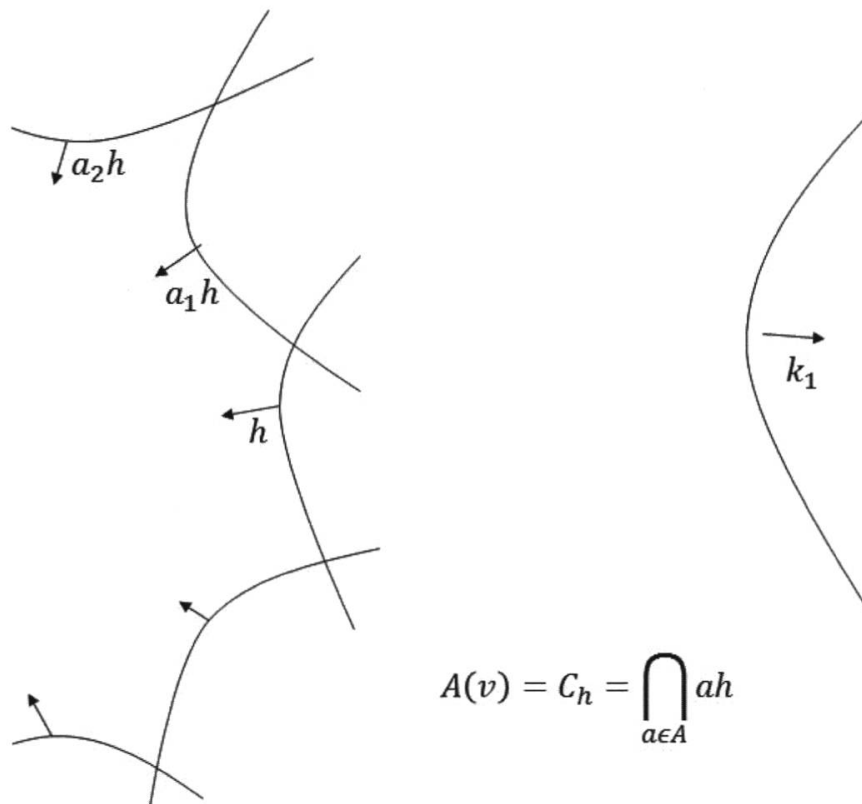


Figure 2. A convex hull for $A(v)$.

Now we consider the natural combinatorial projection of $\hat{\mathfrak{k}}_1$ onto $C_{\mathfrak{h}}$. Namely, consider all the hyperplanes intersecting $C_{\mathfrak{h}}$. As observed, for every such

hyperplane \hat{m} , we have $\hat{\xi}_1 \subset m$ or $\hat{\xi}_1 \subset m^*$. This thus defines an ultrafilter on the collection of hyperplanes meeting C_h , since it is a choice of halfspaces which satisfies the standard consistency conditions necessary for an ultrafilter. It also satisfies the DCC condition (see, for example, [14]). Thus, it determines a vertex w in C_h . This is the unique vertex of C_h that can be joined by a path to $\hat{\xi}_1$ without crossing any hyperplane that meets C_h .

Note that for any $a \in A$, $a\hat{\xi}_1$ does not intersect any hyperplane that intersects $C(h)$. This is because if it did, say $a\hat{\xi}_1 \cap \hat{m} \neq \emptyset$, then by applying a^{-1} , we find that $\hat{\xi}_1 \cap a^{-1}(\hat{m}) \neq \emptyset$. But by invariance of $C(h)$ under A , we have that $a^{-1}(\hat{m}) \cap C(h) \neq \emptyset$, contradicting the strong separation of $\hat{\xi}_1$ and \hat{h} .

Thus $a\hat{\xi}_1$ projects to a vertex in $C(h)$, just as $\hat{\xi}_1$ does. Now by the naturality of this construction, we have that for each $a \in A$, the translate $a\hat{\xi}_1$ projects to aw . But if $a\hat{\xi}_1 \cap \hat{\xi}_1 \neq \emptyset$ it must project to w as well.

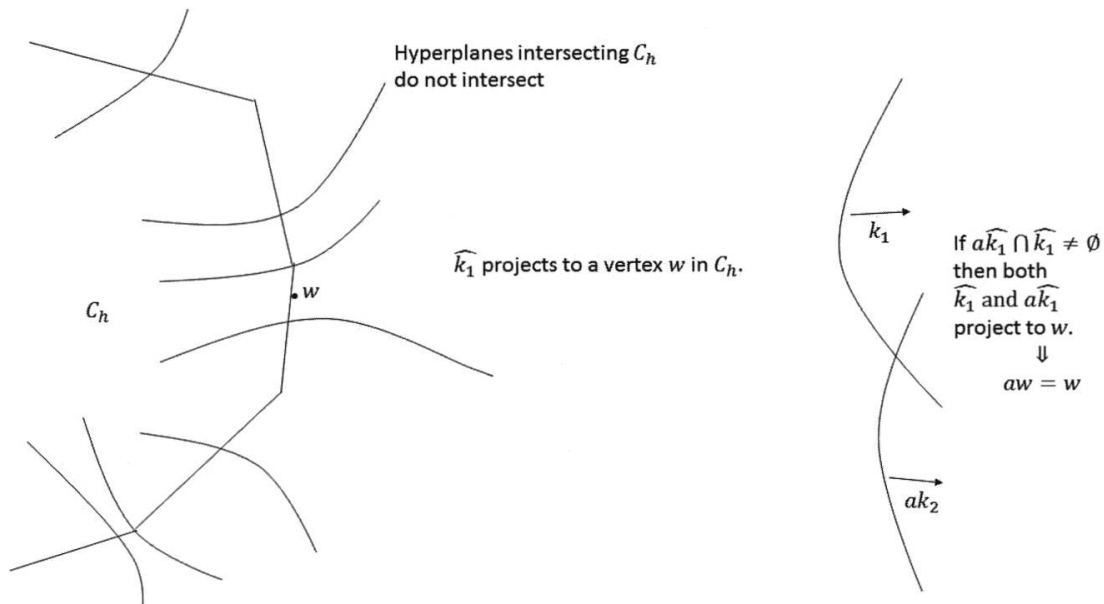


Figure 3. The projection of $\hat{\xi}_1$ onto C_h .

This tells us that

$$S = \{a \in A \mid a\hat{\xi}_1 \cap \hat{\xi}_1 \neq \emptyset\} \subset \text{Stab}(w).$$

By the properness of the action, we get that S is finite. For all elements $a \notin S$, we have $a\xi \subset \xi^*$, as required. We are thus left to prove the proposition for the elements of S .

Let U_{ξ_1} denote the open subset of $S(X)$ determined by ξ_1 . By Lemma 3.3 we can find a point $b \in U_{\hat{\xi}_1}$ which is not fixed by any element of S . Since S is finite, there exists a neighborhood $U \subset U_{\xi_1}$ of b such that $U \cap aU = \emptyset$ for any $a \in S$. Since every open neighborhood contains a halfspace neighborhood, we have a halfspace $\xi_2 \subset \xi_1$ such that $aU_{\xi_2} \cap U_{\xi_2} = \emptyset$ for all $a \in S$. Thus, for any $a \in S$,

we have that $a\mathfrak{k}_2 \subset \mathfrak{k}_2^*$ for any $a \in S$. Since this is already true for \mathfrak{k}_1 for all other elements of A , the hyperplane $\hat{\mathfrak{k}}_2$ is the desired hyperplane.

To show the proposition for the case of finitely many subgroups A_1, \dots, A_n which are simultaneously inessential, we start with a hyperplane \mathfrak{h} such that $\bigcup_i A_i(v) \subset \mathfrak{h}$. Taking $\hat{\mathfrak{k}}_1$ as above we see that the set of elements S of $\bigcup_i A_i$ which carry $\hat{\mathfrak{k}}_1$ to a hyperplane meeting $\hat{\mathfrak{k}}_1$ is finite. We then construct, as in the previous paragraph a halfspace $\mathfrak{k}_2 \subset \mathfrak{k}_1$ such that $a\mathfrak{k}_2 \subset \mathfrak{k}_2^*$ for any element of S . This $\hat{\mathfrak{k}}_2$ is the desired hyperplane. \square

Proof of Theorem 3.1. By Proposition 3.4, there exists a halfspace \mathfrak{k} such that $a\mathfrak{k} \subset \mathfrak{k}^*$ for all $a \in \bigcup_i A_i$. We need to find our $g \in G$ which plays ping-pong with every A_i .

By the Facing Triples Lemma, there exists a pair of disjoint halfspaces m and n with $m \cup n \subset \mathfrak{k}$. By the Double Skewering Lemma, there exists $g \in G$ such that $gm^* \subset n$.

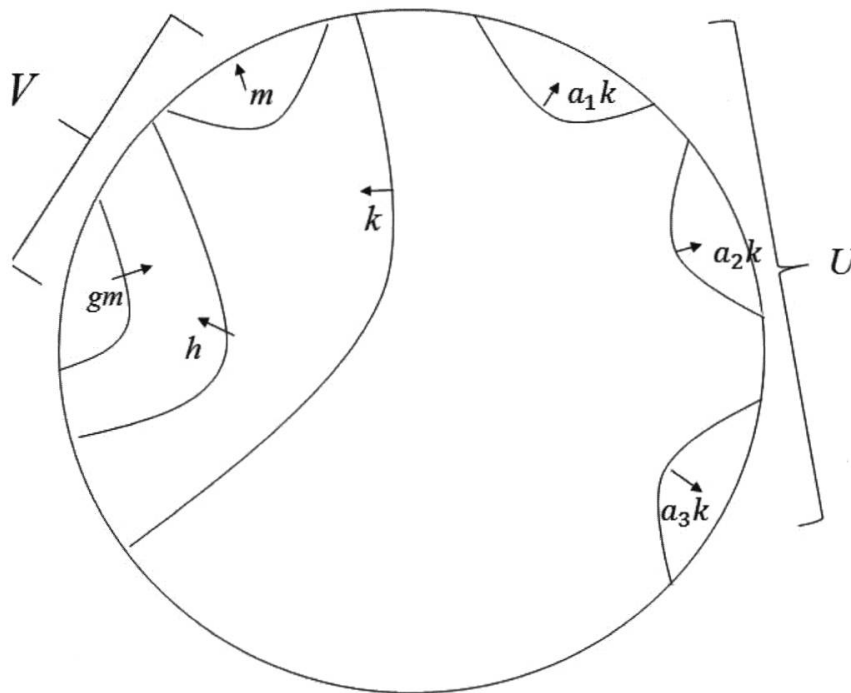


Figure 4. The construction of the ping pong pair.

We now construct two disjoint subsets U and V of X , such that $aU \subset V$ for all non-trivial $a \in A_i$ and $g^n V \subset U$ for all $n \neq 0$ and for all i . This will then give the result by the Ping Pong Lemma. For each i , we define

$$U = \bigcup_{a \neq 1 \in A_i} a\mathfrak{k} \quad \text{and} \quad V = m \cup gm^* .$$

Note that by construction, for each $a \neq 1 \in A_i$, we have $a\mathfrak{k} \subset U$, so we have $aV \subset U$. For each $n \neq 0$, we obtain $g^n(g\mathfrak{m}) \subset \mathfrak{m}$ or $g^n\mathfrak{m}^* \subset g\mathfrak{m}^*$. Since $U \subset \mathfrak{m}^*$ and $U \subset g\mathfrak{m}$, we have that $g^nU \subset V$, as required. \square

We now prove Proposition 2.1.

Proof. We prove the proposition by induction on n . Let v be a vertex of X . In [16, Proposition 3.3], it is shown that if H is a quasiconvex subgroup of G , there exists a number $C > 0$ and a universal number $D > 0$ (depending only on the dimension of the complex), such that if w is a vertex with $d(w, H(v)) > C$, then there exists a hyperplane \hat{h} separating w and $H(v)$ and $d(w, \hat{h}) < D$.

Since points arbitrarily far away from $H(v)$ are guaranteed to exist when H is of infinite index, this implies that the the proposition in the case $n = 1$.

We know assume that G_1, \dots, G_{n-1} are simultaneously inessential. Let \mathfrak{h} be a halfspace such that $G_i(v) \subset \mathfrak{h}^*$ for $i = 1, \dots, n - 1$. Note that since $v \subset \mathfrak{h}^*$, the orbit $G_n(v)$ is not entirely contained in \mathfrak{h} . We consider a halfspace $\mathfrak{k} \subset \mathfrak{h}$ such that $\hat{\mathfrak{k}}$ is strongly separated from $\hat{\mathfrak{h}}$. Since G_n is of infinite index, there exists a vertex $w \in \mathfrak{k}$ such that $d(w, G_n(v)) > C$. We also choose w such that $d(w, \hat{\mathfrak{k}}) > D$. Now we apply the above again and conclude that there exists a hyperplane $\hat{\mathfrak{m}}$ separating w and $G_n(v)$ and such that $d(w, \hat{\mathfrak{m}}) < D$. Let \mathfrak{m} be the halfspace associated to $\hat{\mathfrak{m}}$ such that $w \in \mathfrak{m}$ and $G_n(v) \subset \mathfrak{m}^*$. Since $d(w, \hat{\mathfrak{m}}) < D$, we have that $\hat{\mathfrak{m}} \cap \hat{\mathfrak{k}} \neq \emptyset$. Since $\hat{\mathfrak{k}}$ and $\hat{\mathfrak{h}}$ are strongly separated, we thus have that $\hat{\mathfrak{m}} \cap \hat{\mathfrak{h}} = \emptyset$. Moreover, since $G_n(v) \cap \mathfrak{h}^* \neq \emptyset$, we must have $\mathfrak{m} \subset \mathfrak{h}$ and not $\mathfrak{m}^* \subset \mathfrak{h}$. It follows that $G_i(v) \subset \mathfrak{h}$ for all $i = 1, \dots, n$, as required. \square

We complete the section with a proof of Proposition 1.1, which says that $S(X)$ is a G -boundary, on which, if conditions are favourable, G acts topologically freely.

Proof of Proposition 1.1. Let X be a non-Euclidean irreducible CAT(0) cube complex X . Suppose G is acting essentially on X without a global fixed point at infinity. Then, we claim that $S(X)$ is a G -boundary. We first show that the compact G -space $S(X)$ is minimal: given $\alpha \in S(X)$ and $U \subset S(X)$ open, there exists $g \in G$ such that $g\alpha \in U$. By Lemma 2.9, there exists some halfspace \mathfrak{h} such that $(U_{\mathfrak{h}} \cap S(X)) \subset U$. If $\mathfrak{h} \in \alpha$ then we can take $g = 1$. Suppose then $\mathfrak{h} \notin \alpha$. By the Flipping Lemma [6], there exists $g \in G$ such that $g\mathfrak{h}^* \subset \mathfrak{h}$ and for this g , $\mathfrak{h} \in g\alpha$. This implies $g\alpha \in (U_{\mathfrak{h}} \cap S(X)) \subset U$.

We now show that the $S(X)$ is proximal: for any pair $\alpha, \beta \in S(X)$ of points, there exists a point $\gamma \in S(X)$ such that for every open neighbourhood U of γ there exists $g \in G$ such that $g\alpha, g\beta \in U$. Choose a strongly separated ultrafilter γ which is distinct from both α and β . Let U be any open set containing γ . Note that $S(X)$ is Hausdorff and so we can find an open set V that contains γ but does not contain α and β . The open set $U \cap V$ contains γ and by Lemma 2.9, contains a half-space

neighbourhood $U_{\mathfrak{h}}$. Now, $\mathfrak{h}^* \in \alpha, \beta$, so we use the Flipping Lemma to find $g \in G$ such that $g\mathfrak{h}^* \subset \mathfrak{h}$. Then, $\mathfrak{h} \in g\alpha, g\beta$ and therefore $g\alpha, g\beta \in U$.

To ensure that the proximal minimal G space $S(X)$ is strongly proximal, we need to check that $S(X)$ has contractible neighbourhoods. Let α be a strongly separated ultrafilter and let \mathfrak{h} be a halfspace contained in α . We claim that the open neighbourhood $V := U_{\mathfrak{h}} \cap S(X)$ of α is contractible i.e. there exists $\beta \in S(X)$ such that every open neighbourhood of β contains a translate of V . Choose β to be any strongly separated ultrafilter distinct from α and let U be an open set containing β . As before, choose a halfspace \mathfrak{k} such that $\mathfrak{k} \in \beta$, $\mathfrak{k} \subset \mathfrak{h}^*$ and $U_{\mathfrak{k}} \cap S(X) \subset U$. Use the Flipping Lemma to choose $g \in G$ such that $g\mathfrak{k}^* \subset \mathfrak{k}$. Then, $gV \subset U$.

This shows that $S(X)$ is a minimal and strongly proximal compact G -space. Lemma 3.3 verifies that the action is topologically free whenever the action of G on X is proper and G has no non-trivial finite normal subgroups. \square

4. Property P_{naive} and C^* -simplicity

Recall that a group G has property P_{naive} if for every finite subset $F \subset G$ there exists an element $y \in G$ of infinite order such that given $g \in F$, the subgroup $\langle g, y \rangle$ is isomorphic to the free product $\langle g \rangle * \langle y \rangle$.

The simplest example of a group possessing property P_{naive} is a non-abelian free group F_n . Property P_{naive} was introduced by Bekka, Cowling and de la Harpe as part of their programme to study simplicity of group C^* -algebras [3]. Non-elementary hyperbolic groups have property P_{naive} ; this was proved for torsion-free groups by de la Harpe, and further generalized to relatively hyperbolic groups in [2]. In [3], the authors established P_{naive} for Zariski dense subgroups of connected simple Lie groups with \mathbb{R} -rank 1 and trivial center. More recently, property P_{naive} was studied by Tal Poznansky in the context of linear groups: he proved that every Zariski-dense subgroup of a semisimple algebraic group (over any field), satisfies a weak version of property P_{naive} [13, Lemma 2.3].

Here, we study conditions under which groups acting on CAT(0) cube complexes have property P_{naive} . When the underlying complex is irreducible, property P_{naive} follows from the Main Theorem and is recorded as Corollary 3.2 above.

4.1. Products. In the case of products, we prove a result in a more restricted setting, namely that of lattices in $\text{Aut}(X)$, where X is a locally finite, cocompact cube complex.

Theorem 4.1. *Let X be a locally finite, cocompact CAT(0) cube complex with no Euclidean factors; let G be a lattice in $\text{Aut}(X)$ with no non-trivial finite normal subgroup. Then G satisfies P_{naive} .*

Proof. Let $X = \prod_k X_k$ be the decomposition of X into irreducible factors. Let g_1, \dots, g_n denote a finite collection of elements of G .

We first observe that for each i , the action of $\langle g_i \rangle$ on each irreducible factor of X is inessential. This is simply because $\langle g_i \rangle$ is cyclic and each factor is non-euclidean.

Secondly, we observe that since the action of $\langle g_i \rangle$ is proper, there exists a factor of X on which the action of $\langle g_i \rangle$ is proper. Otherwise, for each factor X_k there exists an integer n_k such that $g_i^{n_k}$ fixes the ball of radius R in X_k . Taking $N = \prod_k n_k$, we obtain an N such that $\langle g_i^N \rangle$ fixes the ball of radius R in each X_k , which in the case that g_i is infinite cyclic, would contradict the properness of the action of $\langle g_i \rangle$ on X .

For each factor X_k for which $\langle g_i \rangle$ acts properly on X_k , Proposition 3.4 insures that there exists a halfspace h_k , such that $ah_k \subset h_k^*$ for all $a \in \langle g_i \rangle$. (If for some k , there are no such g_i 's, we choose h_k arbitrarily.) Following the proof of Theorem 3.1, for each such k , we then choose halfspaces m_k and n_k , so that $m_k \cup n_k \subset h_k$.

Now we apply Theorem 2.5 to conclude that there exists $g \in G$ such that $gm_k^* \subset n_k$ simultaneously for all k . The construction now of U and V for the application of the Ping Pong Lemma proceeds as in the proof of Theorem 3.1.

More precisely, we need to show that $\langle g, g_i \rangle \equiv \langle g \rangle * \langle g_i \rangle$. Given such an i , Let X_k denote an irreducible component on which $\langle g_i \rangle$ acts properly. Then set

$$U = \bigcup_{a \neq 1 \in \langle g_i \rangle} ah_k \quad \text{and} \quad V = m_k \cup n_k.$$

Then we obtain $aV \subset U$ for any $a \neq 1$ and we have $g^n U \subset V$ for any $n \neq 0$, as required. □

4.2. Infinite conjugacy classes. Corollary 3.2 and Theorem 4.1 allow us to determine necessary and sufficient conditions for a CAT(0) cube complex group to be C^* -simple. C^* -simple groups are often *icc*: a group is *icc* if the conjugacy class of every non-identity element is infinite. We will first identify the collection of CAT(0) cubical groups which are *icc*.

Proposition 4.2. *If a group G acts properly and co-compactly on a CAT(0) cube complex then G is *icc* if and only if no finite index subgroup of G contains a non-trivial virtually abelian normal subgroup.*

Proof of Proposition. Suppose that G is not *icc*. Let H be the collection of all elements $g \in G$ such that the conjugacy class of g is finite. It is easy to check that H is a characteristic subgroup of G . Let L be a subgroup generated by finitely many elements x_1, \dots, x_k of H . For each i , the centralizer of x_i in L is a subgroup of finite index in L . Consequently, the centre of L , which is the intersection of the centralizers of the x_i 's has finite index in L . This implies that each finitely generated subgroup

of H is virtually abelian. As every virtually abelian subgroup must stabilize a flat and the dimension of flats in X is bounded, H is forced to be virtually abelian. This shows, if G has a non-trivial finite conjugacy class, then G contains a non-trivial virtually abelian normal subgroup.

Suppose now that a finite index subgroup Γ of G contains a virtually abelian normal subgroup K . If K is finite and g is a non-trivial element of K , then the conjugacy class $\{xgx^{-1} \mid x \in G\}$ of g is contained in $\cup_{t \in G/\Gamma} tKt^{-1}$. Evidently, every conjugacy class of K is finite and so, G cannot be icc. If K is infinite, then replace K by a characteristic subgroup K' which is free abelian of finite rank. The action of Γ on K by conjugation fixes K' and so, Γ normalizes K' . The homomorphism from Γ to $\text{Aut}(K') \cong GL(n, \mathbb{Z})$ has finite image (in fact, it lies inside $O(n) \cap GL(n, \mathbb{Z})$) and so, a finite index subgroup of Γ (and hence, of G) that centralizes K' . Clearly, the conjugacy class of every element of K' in G is finite and G cannot be icc. \square

The amenable radical of a group G , written A_G is the largest amenable normal subgroup of G . As amenability is closed under extensions, the amenable radical exists and is easily shown to be a characteristic subgroup of G . Suppose a group G has a finite index subgroup that contains a normal virtually abelian subgroup K . Then, passing to a normal finite index subgroup, we can assume that G has a normal subgroup H of finite index such that $A_H \neq 1$. As A_H is characteristic in H , it is normal in G and it follows, $A_G \neq 1$. Hence, the triviality of A_G implies that G has no finite index subgroups containing normal virtually abelian subgroups.

In groups acting geometrically on CAT(0) cube complexes the converse is true: the amenable radical is trivial if no finite index subgroup of G has normal virtually abelian subgroups $\neq 1$. This is because, CAT(0) cubical groups satisfy the Tits Alternative [15, Main Theorem] and the amenable radical is virtually abelian. Therefore $A_G \neq 1$ implies G has a normal virtually abelian subgroup. To summarise, we have the following equivalence.

Lemma 4.3. *Suppose that a group G is acting properly on a CAT(0) cube complex and G has a bound on the size of its finite subgroups. Then the amenable radical A_G is trivial iff G has no finite index subgroups with normal non-trivial virtually abelian subgroups.*

The presence of virtually abelian subgroups inside finite index subgroups of G is directly related to the existence of Euclidean factors in the Cartan decomposition of the underlying space.

Lemma 4.4. *Suppose a group G is acting geometrically and faithfully on a CAT(0) cube complex X . If X has a Euclidean factor, then some finite index subgroup of G contains a non-trivial virtually abelian normal subgroup. In particular, the amenable radical of G is non-trivial.*

Proof. As G is acting geometrically, X is finite dimensional and moreover by passing to an essential core, we may assume that the G -action on X is essential. Now, if X is irreducible, then X is Euclidean, meaning, it is quasi-isometric to the real line. In this case G itself is virtually infinite cyclic. If X is reducible, then it has a Cartan decomposition into irreducible factors. We have $X \cong X_P \times X_E$, where X_E is the Euclidean part of X . Then, by Corollary 2.8 from [12], there is a finite index subgroup H of G such that $H = H_E \times H_P$, where H_E acts properly and co-compactly on X_E . This implies that H_E is virtually abelian and so, a finite index subgroup contains a non-trivial virtually abelian normal subgroup. \square

C^* -simple groups. Let G be a countable discrete group and let $\ell^2 G$ be the Hilbert space of square-summable functions on G . The group G acts on $\ell^2 G$ via its left regular representation as follows.

$$\lambda_g(f)(h) = f(g^{-1}h), \quad \forall g, h \in G.$$

The map $g \mapsto \lambda_g$ gives an injection of G into the space of bounded linear operators $\mathcal{B}(\ell^2 G)$. The closure of the linear span of image $\{\lambda_g : g \in G\}$ in the operator norm is called the reduced C^* -algebra of G and written, $C_r^*(G)$.

A countable group is said to be C^* -simple if $C_r^*(G)$ is a simple algebra, i.e. $C_r^*(G)$ has no non-trivial two-sided ideals. The reduced C^* -algebra carries information about the representation theory of the group. One can show that simplicity of the algebra $C_r^*(G)$ is equivalent to the following restriction on the representation theory of G : every unitary representation of G which is weakly contained in the left regular representation of G is actually equivalent to it. This means that a group which is both amenable and C^* -simple must be the trivial group. This statement in turn generalizes to the fact that a C^* -simple group cannot have non-trivial normal amenable subgroups.

Many geometric classes of groups have been shown to be C^* -simple. These include all free products (except the infinite dihedral group), non-soluble subgroups of $\mathrm{PSL}_2(\mathbb{R})$, torsion-free non-elementary hyperbolic groups and mapping class groups of surfaces. More generally, acylindrically hyperbolic groups are C^* -simple [7].

A group acting geometrically on an irreducible CAT(0) cube complex has enough rank one elements to make it acylindrically hyperbolic, using results from [17]. So groups acting geometrically on irreducible CAT(0) cubical groups are C^* -simple. However a group acting geometrically on a non-trivial product of irreducibles is not acylindrically hyperbolic (for example, irreducible lattices in products of trees). Here, we apply our theorems on property P_{naive} to show that even in this setting, a group G acting properly and co-compactly on a CAT(0) cube complex is C^* -simple. We summarize this as follows.

Theorem 4.5 (Corollary 1.4). *Suppose that a group G is acting properly and co-compactly on a CAT(0) cube complex X . The following are equivalent.*

- (1) G is C^* simple.
- (2) G is icc.
- (3) No finite index subgroup of G has a non-trivial virtually abelian normal subgroup.
- (4) the amenable radical of G is trivial.
- (5) The G -action is faithful and X is non-Euclidean.
- (6) G has property P_{naive} .

Proof. The implications (1) \Rightarrow (2) and (6) \Rightarrow (1) are well known, see [3]. Proposition 4.2 establishes the equivalence of (2) and (3). Lemma 4.3 shows (3) and (4) are equivalent. That (4) implies (5) follows from Lemma 4.4.

The hypothesis that G acts properly and co-compactly implies that G is finitely presented and moreover, X is finite-dimensional. The kernel of the action is finite whenever the action is proper and so if the amenable radical is trivial, the action is faithful. Now, to deduce (6) from (5), after passing to an essential core if needed, we apply Corollary 3.2 and Theorem 4.1. \square

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