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A new line associated with the triangle

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Let ABC be any triangle in the Euclidean plane \mathbb{E} with side-lengths a , b , and c , and with angles A , B , and C , in the standard order. Let X , Y , and Z be points on the sidelines BC , CA , and AB , respectively. A fairly well-known theorem of Ceva states that the cevians AX , BY , and CZ are concurrent if and only if the cevian relation

$$(BX)(CY)(AZ) = -(CX)(AY)(BZ) \quad (1)$$

holds, where UV denotes the directed distance between the points U and V . Here, a *cevia*n is a line that joins a vertex to a point on the opposite side. Less known is the fact that the perpendiculars erected from the points X , Y , and Z on their respective sides, as

Fällt man von einem Punkt P aus die Lote auf die drei Seiten eines Dreiecks ABC , so bestimmen die Fusspunkte X , Y , Z auf diesen Seiten die entsprechenden Seitenabschnitte \overline{BX} , \overline{CY} , \overline{AZ} . Es stellt sich heraus, dass der geometrische Ort aller Punkte P , für welche diese Seitenabschnitte sich als Linearformen der Längen a , b , c der Dreiecksseiten ausdrücken lassen, die Gerade durch die Zentren \mathcal{I} und \mathcal{O} des In- bzw. des Umkreises ist. Dies ergänzt die Ergebnisse, dass die Gerade durch \mathcal{I} und den Schwerpunkt \mathcal{G} des Dreiecks der geometrische Ort der Punkte ist, deren baryzentrische Koordinaten projektiv linear in a , b , c sind und dass die Eulergerade durch \mathcal{O} und \mathcal{G} der geometrische Ort der Punkte ist, deren baryzentrische Koordinaten projektiv linear in $\tan A$, $\tan B$, $\tan C$ sind. Ausserdem generieren die Autoren durch Untersuchung der Geraden durch \mathcal{I} , \mathcal{O} und \mathcal{G} zusätzliche spezielle Punkte des Dreiecks ABC , die im Kimberling-Katalog der „Dreieckszentren“ nicht aufgeführt sind.

shown in Fig. 1, are concurrent if and only if the condition

$$(BX)^2 + (CY)^2 + (AZ)^2 = (CX)^2 + (AY)^2 + (BZ)^2 \quad (2)$$

holds; see, for example, [13] and [7, Theorem 6.3.1, p. 96].

Following [22], a *center* or a *center function* is defined to be a mapping that assigns to every non-degenerate triangle in the Euclidean plane \mathbb{E} a point in \mathbb{E} in a manner that is symmetric and that respects isometries and dilations. More precisely, a center function \mathcal{Z} satisfies the following properties:

- (i) $\mathcal{Z}(\sigma(A), \sigma(B), \sigma(C)) = \mathcal{Z}(A, B, C)$ for all permutations σ on $\{A, B, C\}$.
- (ii) $\mathcal{Z}(\varphi(A), \varphi(B), \varphi(C)) = \varphi(\mathcal{Z}(A, B, C))$ for all isometries φ of \mathbb{E} .
- (iii) $\mathcal{Z}(\lambda A, \lambda B, \lambda C) = \lambda \mathcal{Z}(A, B, C)$ for all real numbers λ .

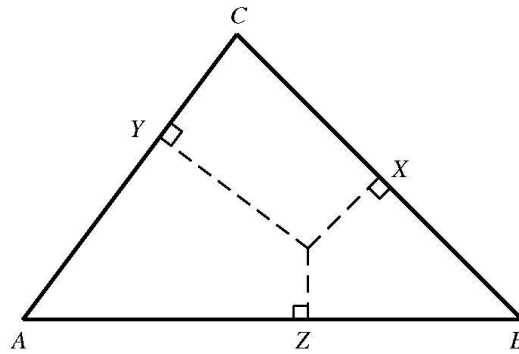


Fig. 1

Let P be a center of triangle ABC , and let X , Y , and Z be the orthogonal projections of P on the sidelines BC , CA , and AB , respectively. If the lengths BX , CY , and AZ are linear forms in a , b , and c , then it follows fairly easily from properties of center functions that the directed lengths of the segments BX , etc., are given by

$$BX = \frac{a}{2} + t(b - c), \quad CY = \frac{b}{2} + t(c - a), \quad AZ = \frac{c}{2} + t(a - b) \quad (3)$$

$$CX = \frac{a}{2} - t(b - c), \quad AY = \frac{b}{2} - t(c - a), \quad BZ = \frac{c}{2} - t(a - b) \quad (4)$$

for some $t \in \mathbb{R}$; see the proof of [1, Theorem 1]. Plugging these values in (2), we obtain what, unexpectedly, turns out to be an identity that holds for all t ; namely the identity

$$\begin{aligned} & \left(\frac{a}{2} + t(b - c)\right)^2 + \left(\frac{b}{2} + t(c - a)\right)^2 + \left(\frac{c}{2} + t(a - b)\right)^2 \\ &= \left(\frac{a}{2} - t(b - c)\right)^2 + \left(\frac{b}{2} - t(c - a)\right)^2 + \left(\frac{c}{2} - t(a - b)\right)^2. \end{aligned}$$

Thus every $t \in \mathbb{R}$ defines a center P_t in the manner described. Specifically, given $t \in \mathbb{R}$, we locate the points X , Y , and Z on the sidelines according to (3) and (4), and we let P_t be the point of concurrence of the perpendiculars erected from these points on the respective sidelines.

The centers P_t just defined were investigated in [3, Section 9]. There, the authors noted that the centers corresponding to the values $t = 0$, $t = -1/2$ and $t = 1/2$ are the circumcenter, the incenter, and what is referred to in [22] as the Bevan point, and they raised the following question:

Question. What is the curve that the centers P_t trace as t varies?

In the theorem below, we answer this question and we prove that the curve in question is, amazingly, a straight line. We also consider those centers for which the angles of XYZ are linear forms in the angles of ABC .

Before stating and proving the main theorem, we remind the reader that the Gergonne (respectively, Nagel) center of triangle ABC is the point of concurrence of the cevians AA' , BB' , and CC' , where A' , B' , C' are the points where the incircle (respectively, the excircles) touch(es) the sides of ABC . That such cevians are concurrent follows from the cevian condition (1). We also point out that the cevian analogue to the above question has an extremely different answer. Specifically, it is shown in [1, Theorem 1] that the only centers of ABC through which the cevians AA' , BB' , CC' are such that BA' , CB' , and AC' are linear forms in a , b , and c are the centroid, the Gergonne center, and the Nagel center. This heavy contrast stems from the fact that the cevian condition (1) takes the form

$$\begin{aligned} & \left(\frac{a}{2} + t(b-c)\right)\left(\frac{b}{2} + t(c-a)\right)\left(\frac{c}{2} + t(a-b)\right) \\ &= \left(\frac{a}{2} - t(b-c)\right)\left(\frac{b}{2} - t(c-a)\right)\left(\frac{c}{2} - t(a-b)\right) \end{aligned}$$

and has three solutions only, namely $t = -1/2$, $t = 0$, and $t = 1/2$. Similarly, the only centers for which $\angle BAA'$, $\angle CBB'$, and $\angle ACC'$ are linear forms in A , B , and C are the circumcenter, the incenter, and the orthocenter, and the only centers for which $\angle AC'B'$, $\angle BA'C'$, and $\angle CB'A'$ are linear in A , B , and C are the centroid, the orthocenter, and the Nagel center; see [1, Theorem 2] and [2, Theorem 7]. Similar issues are addressed in [17] and [4].

Theorem. *Let ABC be a non-degenerate triangle with side-lengths a , b , and c in the standard order. For a point P in the plane of ABC , let X , Y , and Z be the projections of P on the sides BC , CA , and AB , respectively. Then the centers for which BX , CY , and AZ are linear forms in a , b , and c form the straight line that joins the circumcenter and the incenter.*

Proof. As seen earlier, the centers in question are precisely the centers $P = P_t$ whose projections $X = X_t$, $Y = Y_t$, and $Z = Z_t$ on the sides BC , CA , and AB satisfy (3) and (4) for some t .

Using the lengths of $XB = X_t B$ and $XC = X_t C$ as given in (3) and (4), we write X_t as a convex combination

$$X_t = \frac{1}{a} \left[\left(\frac{a}{2} + t(b-c) \right) C + \left(\frac{a}{2} - t(b-c) \right) B \right]$$

of the points B and C . Multiplying by $2a$ and simplifying, we obtain

$$2aX_t = a(C+B) + 2t(b-c)(C-B). \quad (5)$$

Since $P_t - X_t$ is perpendicular to $C - B$, it follows that $P_t \cdot (C - B) = X_t \cdot (C - B)$. Here, we have treated points in the plane as position vectors and we have used the ordinary scalar product. Without loss in generality, we shall assume that the circumcenter P_0 of ABC lies at the origin O and that its circumradius is 1. Then

$$\begin{aligned} 2a P_t \cdot (C - B) &= 2a X_t \cdot (C - B) \\ &= (a(C+B) + 2t(b-c)(C-B)) \cdot (C-B), \text{ by (5)} \\ &= a(C \cdot C - B \cdot B) + 2t(b-c)(C-B) \cdot (C-B) \\ &= 2t(b-c)a^2, \text{ because } \|C\| = \|B\| = 1 \text{ and } \|C-B\| = a. \end{aligned}$$

From this and symmetry, we conclude that

$$P_t \cdot (C - B) = ta(b-c), \quad P_t \cdot (A - C) = tb(c-a), \quad P_t \cdot (B - A) = tc(a-b). \quad (6)$$

We shall now compute the distance $\|P_t - P_0\| = \|P_t\|$ between P_t and the circumcenter P_0 and see that it is a constant multiple of $|t|$.

To compute $\|P_t\|$, we let $D = [P_t \quad C - B \quad A - C]$ be the 2×3 matrix whose columns represent the coordinates of the vectors P_t , $C - B$, and $A - C$ (with respect to some basis), and we consider the 3×3 matrix $D^T D$, where D^T denotes the transpose of D . Since $\text{rank}(D) \leq 2$ (in fact $= 2$, since $C - B$ and $A - C$ are linearly independent), it follows from the general fact $\text{rank}(UV) \leq \text{rank}(U)$ that $\text{rank}(D^T D) \leq 2$ and that $\det(D^T D) = 0$. Therefore

$$\begin{aligned} 0 &= \det(D^T D) \\ &= \det \left(\begin{bmatrix} P_t & C - B & A - C \end{bmatrix}^T \begin{bmatrix} P_t & C - B & A - C \end{bmatrix} \right) \\ &= \det \begin{bmatrix} P_t \cdot P_t & P_t \cdot (C - B) & P_t \cdot (A - C) \\ P_t \cdot (C - B) & (C - B) \cdot (C - B) & (C - B) \cdot (A - C) \\ P_t \cdot (A - C) & (A - C) \cdot (C - B) & (A - C) \cdot (A - C) \end{bmatrix} \\ &= \begin{vmatrix} P_t \cdot P_t & ta(b-c) & tb(c-a) \\ ta(b-c) & a^2 & Q \\ tb(c-a) & Q & b^2 \end{vmatrix}, \text{ by (6) and where } Q = (C - B) \cdot (A - C) \\ &= \|P_t\|^2 \begin{vmatrix} a^2 & Q \\ Q & b^2 \end{vmatrix} - ta(b-c) \begin{vmatrix} ta(b-c) & Q \\ tb(c-a) & b^2 \end{vmatrix} + tb(c-a) \begin{vmatrix} ta(b-c) & a^2 \\ tb(c-a) & Q \end{vmatrix} \\ &= \|P_t\|^2 \begin{vmatrix} a^2 & Q \\ Q & b^2 \end{vmatrix} - t^2 a(b-c) \begin{vmatrix} a(b-c) & Q \\ b(c-a) & b^2 \end{vmatrix} + t^2 b(c-a) \begin{vmatrix} a(b-c) & a^2 \\ b(c-a) & Q \end{vmatrix}. \end{aligned}$$

The right-hand side has the form $\|P_t\|^2 G - t^2 H$, where G and H do not depend on t . Therefore $\|P_t\|^2 = t^2 F$, where F does not depend on t , and hence the distance between P_t and $P_0 = O$ is a constant multiple of $|t|$. Since the length of the projection of the segment $P_t P_0$ on BC is also a constant multiple of $|t|$, being nothing but $|t||b - c|$, we conclude that the absolute value of the slope of $P_t P_0$, relative to BC , is independent of t . It follows that the slope of $P_t P_0$ is independent of t . In fact, if $b > c > a$, then X_t moves towards C and Y_t towards A , showing that the slope is positive and hence does not change sign. Thus P_t moves on a straight line, necessarily the line joining the circumcenter P_0 and the incenter $P_{-1/2}$. \square

Remarks. (i) To find a formula for $\|P_t\|$, one uses the Law of Cosines to obtain

$$2Q = 2(C - B) \cdot (A - C) = -2ab \cos C = c^2 - a^2 - b^2,$$

and then plugs this in the determinant above. The result should of course be multiplied by the circumradius R to make up for our assumption that $R = 1$. In view of Euler's formula $d^2 = R(R - 2r)$, where R is the circumradius, r the inradius, and d the distance between the circumcenter and the incenter, one expects to get

$$\|P_t\|^2 = 4t^2 \|P_{-1/2}\|^2 = 4t^2 d^2 = 4t^2 R(R - 2r).$$

(ii) Letting X, Y , and Z be as in the theorem, one may consider those centers for which the angles of the pedal triangle XYZ are linear forms in A, B , and C . Since

$$\angle ZXY = \angle ZXP + \angle YXP = \angle ZBP + \angle YCP = \angle BPC - A,$$

it follows that these are precisely the centers P for which the angles $\angle BPC, \angle CPA$, and $\angle APB$ are linear forms in A, B , and C . These centers are the subject of study in [17], where the curve they trace is called the Balaton curve and where the complex behaviour of this curve is fully described.

(iii) Let the centroid, the circumcenter, and the incenter of ABC be denoted, respectively, by \mathcal{G}, \mathcal{O} , and \mathcal{I} . It is shown in [4] that the locus of the centers of ABC whose barycentric coordinates are projective linear functions in a, b , and c is the straight line $L(\mathcal{G}, \mathcal{I})$. It is also noted there that the Euler line $L(\mathcal{G}, \mathcal{O})$ is the locus of the centers of ABC whose barycentric coordinates are projective linear functions in $\tan A, \tan B$, and $\tan C$. It follows that

$$L(\mathcal{G}, \mathcal{I}) \parallel BC \iff 2a = b + c, \tag{7}$$

$$L(\mathcal{G}, \mathcal{O}) \parallel BC \iff 2 \tan A = \tan B + \tan C. \tag{8}$$

A condition for $L(\mathcal{O}, \mathcal{I})$ to be parallel to BC can be found by setting the slope of $L(\mathcal{O}, \mathcal{I})$ equal to 0. More directly, we let r and R be the inradius and circumradius of ABC , and

we see that

$$\begin{aligned}
 L(\mathcal{O}, \mathcal{I}) \parallel BC &\iff \text{the areas of triangles } \mathcal{O}BC \text{ and } \mathcal{I}BC \text{ are equal} \\
 &\iff \frac{ra}{2} = \frac{R^2 \sin 2A}{2} \\
 &\iff ra = 2R^2 \sin A \cos A \\
 &\iff \frac{r}{R} = \cos A, \text{ because } 2R = \frac{a}{\sin A} \\
 &\iff \cos A + \cos B + \cos C - 1 = \cos A, \text{ by Carnot's formula [24]} \\
 &\iff \cos B + \cos C = 1.
 \end{aligned}$$

Thus we have proved that

$$L(\mathcal{O}, \mathcal{I}) \parallel BC \iff \cos B + \cos C = 1. \tag{9}$$

For earlier references related to (7), see [20, Problem 82, p. 209], [8], [10], [14], [25], and [12]. For (8), see [15, Problem 9, p. 18], [11], and [6], where [6] also describes the locus of A when ABC is a triangle having a fixed base BC and satisfying $2 \tan A = \tan B + \tan C$. For (9), see [26] and [19], where [19, Corollary 4] gives another geometric characterization of the condition $L(\mathcal{O}, \mathcal{I}) \parallel BC$.

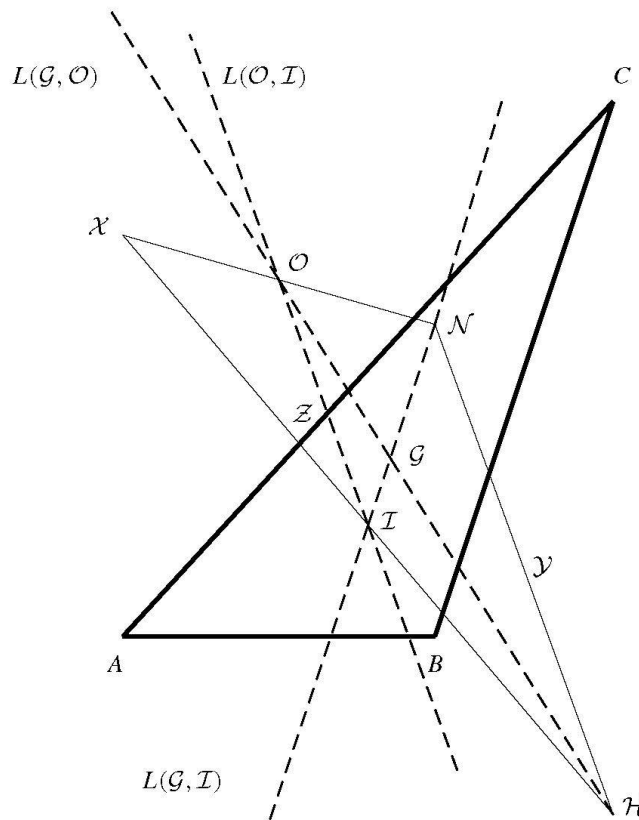


Fig. 2

(iv) In [28, Exercise 5.7], the area of the triangle $\mathcal{G}\mathcal{O}\mathcal{I}$ is given by the elegant formula

$$[\mathcal{G}\mathcal{O}\mathcal{I}] = \left| \frac{s(b-c)(c-a)(a-b)}{24K} \right|,$$

where s is the semiperimeter and K the area of ABC . An equivalent formula is given in [5, Section 4.4, pp. 105–106]. It follows that two (and hence all) of the three lines $L(\mathcal{G}, \mathcal{O})$, $L(\mathcal{G}, \mathcal{I})$, and $L(\mathcal{O}, \mathcal{I})$ coincide if and only if ABC is isosceles. A more geometric proof is given in [21, Section 11, problem 4, pp. 142–144]. Also, a generalization to higher dimensional orthocentric simplices is given in [18].

(v) The lines $L(\mathcal{G}, \mathcal{O})$, $L(\mathcal{G}, \mathcal{I})$, and $L(\mathcal{O}, \mathcal{I})$, together with several centers that they contain and the relative locations of these centers, are shown in Fig. 2. This figure shows the similarity between the Euler line $L(\mathcal{G}, \mathcal{O})$ and its rival $L(\mathcal{G}, \mathcal{I})$ and locates them as two medians of a triangle two of whose vertices are the orthocenter \mathcal{H} and the Nagel center \mathcal{N} . The third vertex is labelled \mathcal{X} and it does not seem to be a known center. This configuration points to two more centers, other than \mathcal{X} , that are denoted by \mathcal{Y} (the midpoint of $\mathcal{H}\mathcal{N}$) and \mathcal{Z} (the midpoint of $\mathcal{O}\mathcal{I}$). We wonder whether these centers as well as the many lines that appear in this configuration are not already catalogued in [22].

(vi) According to [23], the line $L(\mathcal{O}, \mathcal{I})$ passes through 68 centers that include the Bevan point X_{40} and the points X_{46} , X_{56} , X_{165} , and X_{35} . The trilinear equation of $L(\mathcal{O}, \mathcal{I})$ is

$$(\cos B - \cos C) \alpha + (\cos C - \cos A) \beta + (\cos A - \cos B) \gamma = 0.$$

In view of the fact that $(\cos B - \cos C, \cos C - \cos A, \cos A - \cos B)$ are trilinear coordinates of X_{109} , $L(\mathcal{O}, \mathcal{I})$ is the central line that should be denoted by L_{109} . For more on central lines, see [27].

In the two recent papers [16] and [19], the line $L(\mathcal{O}, \mathcal{I})$ is called the $O\mathcal{I}$ -line, and some of its properties are explored. According to [16], the point X_{57} also lies on the $O\mathcal{I}$ -line. It is also proved in [19, Lemma 2] that the orthocenter of the intouch triangle, or equivalently the orthocenter of the cevian triangle of the Gergonne point, lies on the $O\mathcal{I}$ -line. One wonders whether this center is already catalogued in [22] and [23].

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