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(1.10) and Lemma 1.2 yield

(1.11)
$$\delta_m = \frac{1}{|G|} \sum_{\sigma \in G} (Tr \, \sigma)_m = \frac{1}{|G|} \sum_{\sigma \in G} \sum_{|a|=m} \omega^a(\sigma).$$

Multiply both sides of (1.11) by t^m and sum over m from 0 to ∞ . We get

$$\sum_{m=0}^{\infty} \delta_m t^m = \frac{1}{|G|} \sum_{m=0}^{\infty} \sum_{\sigma \in G} \sum_{|a|=m}^{\infty} \omega^a(\sigma) t^m$$

$$= \frac{1}{|G|} \sum_{\sigma \in G} \left\{ \sum_{m=0}^{\infty} \omega_1^m(\sigma) t^m \dots \sum_{m=0}^{\infty} \omega_n^m(\sigma) t^m \right\}$$

$$= \frac{1}{|G|} \sum_{\sigma \in G} \frac{1}{(1 - \omega_1(\sigma) t) \dots (1 - \omega_n(\sigma) t)}$$

CHAPTER II

INVARIANT THEORETIC CHARACTERIZATION OF FINITE REFLECTION GROUPS

1. CHEVALLEY'S THEOREM

We showed in chapter I that we can always find a finite number of homogeneous invariants forming a basis for the invariants of G and that this set must contain at least n elements, where $n = \dim V$. We show that this lower bound is attained only for the finite reflection groups. We first define these groups.

DEFINITION 2.1. Let σ be a linear transformation acting on the *n*-dimensional vector space V. σ is a reflection $\Leftrightarrow \sigma$ fixes an n-1 dimensional hyperplane π and σ is of finite order > 1. π is called the reflecting hyperplane (r.h.) of σ .

REMARK. Choose $v \notin \pi$ and let $\sigma v = \zeta v + p$, $p \in \pi$. If $\zeta = 1$, then $\sigma^m v = v + mp$, contradicting that σ is of finite order. Hence $\zeta \neq 1$. Let $v' = v + (\zeta - 1)^{-1} p$ and choose $p_1, ..., p_{n-1}$ as a basis for π . Then $\sigma p_i = p_i$, $1 \le i \le n-1$, $\sigma v' = \zeta v'$. ζ is a root of 1 in k which is distinct from 1, as σ is of finite order > 1. Thus σ is a reflection iff relative to some basis, the matrix for σ is diagonal, n-1 of the diagonal entries equalling 1 and the remaining one equalling a root of 1 in k distinct from 1.

DEFINITION 2.2. G is a finite reflection group acting on $V \Leftrightarrow G$ is a finite group generated by reflections on V.

As an example of a finite reflection group, let $G = S_n$. It is well known that S_n is generated by transpositions. The transposition of the variables x_i , x_j ($i \neq j$) fixes the hyperplane $x_i - x_j = 0$, so that it is a reflection.

We have the following result

Theorem 2.1 (Chevalley [4]). Let G be a finite reflection group acting on the n-dimensional vector space V. The invariants of G have a basis consisting of n homogeneous elements which are algebraically independent over k.

Let k[x] denote the ring of polynomials in $x_i, ..., x_n$ with coefficients in k. We prove the following.

LEMMA 2.1. Let $I_1, ..., I_m$ be invariant polynomials of $G, I_1 \notin (I_2, ..., I_m)$ = the ideal in k[x] generated by $I_2, ..., I_m$. Suppose that $P_1 I_1 + ... + P_m I_m = 0$, the P_i 's being polynomials with P_1 homogeneous. Then $P_1 \in \mathcal{I}$, where \mathcal{I} is the ideal in k[x] generated by the homogeneous invariants of positive degree.

Proof of Lemma 2.1. The proof proceeds by induction on $\deg P_1$. Suppose $\deg P_1=0$, so that $P_1=c\in k$. If $c\neq 0$, then $I_1\in (I_2,...,I_m)$, contrary to assumption. Hence $c=0\Rightarrow P_1\in \mathscr{I}$. Let $\deg P_1=n>0$. Let σ be a reflection in G and L=0 the equation of its r.h. (L is a linear homogeneous polynomial). We have $P_1(x)I_1(x)+...+P_m(x)I_m(x)=0$, $P_1(\sigma x)I_1(x)+...+P_m(\sigma x)I_m(x)=0$. Hence $\begin{bmatrix} P_1(\sigma x)-P_1(x)\end{bmatrix}I_1(x)+...+\begin{bmatrix} P_m(\sigma x)-P_m(x)\end{bmatrix}I_m(x)$. For L(x)=0, $\sigma(x)=x$, so that $P_i(\sigma x)-P_i(x)=0$ whenever L(x)=0, $1\leqslant i\leqslant m$. Since L(x) is irreducible it follows that

$$\frac{P_i\left(\sigma x\right) - P_i\left(x\right)}{L(x)}$$

is a polynomial, $1 \le i \le m$. We have

$$\label{eq:local_equation} \begin{split} \left[\frac{P_1\left(\sigma x\right) \,-\, P_1\left(x\right)}{L\left(x\right)}\right] \,I_1\left(x\right) \,+\, \ldots \,+\, \left[\frac{P_m\left(\sigma x\right) \,-\, P_m\left(x\right)}{L\left(x\right)}\right] \,I_m\left(x\right) \,=\, 0 \;. \\ \deg \, \left[\frac{P_1\left(\sigma x\right) \,-\, P_1\left(x\right)}{L\left(x\right)}\right] \,\,<\, \deg \, P_1\left(x\right) \;, \end{split}$$

so that by the induction hypothesis

$$\frac{P_1(\sigma x) - P_1(x)}{L(x)} \equiv 0 \pmod{\mathscr{I}}.$$

Hence $P_1(\sigma x) \equiv P_1(x) \pmod{\mathscr{I}}$. Since the σ 's generate G, this congruence holds for $\sigma \in G$. We conclude that

$$P_1(x) \equiv \frac{1}{|G|} \sum_{\sigma \in G} P_1(\sigma x) \pmod{\mathscr{I}}.$$

The polynomial $\frac{1}{|G|} \sum_{\sigma \in G} P_1(\sigma x)$ is invariant and homogeneous of degree $n \ge 1$. Hence it $\in \mathcal{I}$, so that $P_1 \in \mathcal{I}$.

Proof of Theorem 2.1. We choose $I_1, ..., I_r$ to be homogeneous invariants of positive degree forming a minimal basis for \mathcal{I} . Hilbert's proof of Theorem 1.1 shows that $I_1, ..., I_r$ form a basis for the invariants of G. We show that $I_1, ..., I_r$ are algebraically independent, so that r = n.

Suppose, to the contrary, that $I_1, ..., I_r$ are algebraically dependent. Choose $H(y_1, ..., y_r)$ to be a polynomial of minimal positive degree so that $H(I_1(x), ..., I_r(x)) = 0$. Let x-degree of any monomial $y_1^{a_1} ... y_r^{a_r}$ be $d_1 a_1 + ... + d_r a_r$, where $d_i = \deg I_i$. We may assume that all x-degrees of the monomials appearing in H are the same. Let

$$H_{i}\left(x\right) = \frac{\partial H}{\partial y_{i}}\left(I_{1}\left(x\right), ..., I_{r}\left(x\right)\right), \ 1 \leqslant i \leqslant r.$$

The H_i 's are invariant homogeneous polynomials, as all monomials in H have equal x-degree. Since $H(y_1, ..., y_n)$ is of positive degree, some $\frac{\partial H}{\partial y_i} \neq 0$, It follows that the corresponding $H_i(x) \neq 0$, as H was chosen to be of minimal degree; i.e. not all H_i 's = 0. We relabel indices so that $H_1, ..., H_s, 1 \leq s \leq r$, are ideally independent (i.e. none of the H_i 's is in the ideal generated by the others) and $H_{s+j} \in (H_1, ..., H_s)$. $1 \leq j \leq r - s$. Thus $H_{s+j} = \sum_{i=1}^{s} V_{ji} H_i$, $1 \leq j \leq r - s$, where each V_{ji} is a homogeneous polynomial of degree $d_i - d_{s+j} (V_{ji}$ is interpreted to be 0 if this degree is negative). Differentiating the relation $H(I_1(x), ..., I_r(x)) = 0$ with respect to x_k , we obtain

(2.1)
$$\sum_{i=1}^{r} H_{i} \frac{\partial I_{i}}{\partial x_{k}} = \sum_{i=1}^{s} H_{i} \frac{\partial I_{i}}{\partial x_{k}} + \sum_{l=1}^{r-s} H_{s+l} \frac{\partial I_{s+l}}{\partial x_{k}}$$
$$= \sum_{i=1}^{s} H_{i} \left[\frac{\partial I_{i}}{\partial x_{k}} + \sum_{l=1}^{r-s} V_{li} \frac{\partial I_{s+l}}{\partial x_{k}} \right] = 0.$$

Since

$$\frac{\partial I_i}{\partial x_k} + \sum_{l=1}^{r-s} V_{li} \frac{\partial I_{s+l}}{\partial x_k}$$

is homogeneous of degree $d_i - 1$, we conclude from Lemma 2.1 that

(2.2)
$$\frac{\partial I_i}{\partial x_k} + \sum_{l=1}^{r-s} V_{li} \frac{\partial I_{s+l}}{\partial x_k} = \sum_{j=1}^r B_j I_j, \ 1 \leqslant i \leqslant s,$$

where the B_j 's are homogeneous and each term in (2.2) is homogeneous of degree $d_i - 1$. This forces $B_i = 0$. Multiply both sides of (2.2) by x_k and sum over k. We conclude, by Euler's identity for homogeneous polynomials,

(2.3)
$$d_i I_i + \sum_{l=1}^{r-s} V_{li} d_{s+l} I_{s+l} = \sum_{j=1}^{r} A_j I_j ,$$

the A_i 's being homogeneous with $A_i = 0$.

(2.3) shows that $I_i \in (I_1, ..., I_{i-1}, I_{i+1}, ..., I_r)$, contradicting the minimality of the basis $I_1, ..., I_r$. Hence $I_1, ..., I_r$ are algebraically independent and r = n.

2. The Theorem of Shephard and Todd

We obtain in this section a converse to Chevalley's Theorem, thereby obtaining an invariant theoretical characterization of finite reflection groups. We first prove several preliminary results.

LEMMA 2.2. Let H be a finite group of linear transformations acting on the n-dimensional space V and fixing the n-1 dimensional hyperplane π . The elements of H have a common eigenvector $v \in V - \pi$. Let $\sigma(v) = \zeta(\sigma)v$, $\sigma \in H$. $\zeta(\sigma)$ is an isomorphism from H into the multiplicative group of the roots of unity in k. It follows that H is a cyclic group.

REMARK. The above lemma is a consequence of Maschke's Theorem proven in section 2.3. We provide another proof below.

Proof. Let $\sigma_1 \in H$, $\sigma_1 \neq e$ (the identity of H). By the remark following Definition 2.1, there exists $v \in V - \pi$ such that $\sigma_1(v) = \zeta_1 v$, ζ_1 being a root of unity $\neq 1$. For $\sigma \in H$, let $\sigma(v) = \zeta(\sigma)v + p(\sigma)$, $\zeta(\sigma) \in k$ and $p(\sigma) \in \pi$. Let $\sigma^* = \sigma_1^{-1} \sigma^{-1} \sigma_1 \sigma$. Then $\sigma^*(v) = v + (1 - \zeta_1) p(\sigma)$. Since σ^* is of finite order, $(1 - \zeta_1) p(\sigma) = 0 \Rightarrow p(\sigma) = 0$. Hence $\sigma(v) = \zeta(\sigma) v$. $\zeta(\sigma)$ is clearly an isomorphism from H into U, the multiplicative group of

the roots of unity in k. U is known to be cyclic ([22], Vol. 1, p. 112). It follows that $\zeta(H)$, a subgroup of U, is cyclic and so H is cyclic.

Theorem 2.2. Let G be a finite group acting on the n-dimensional space V. Let $I_1, ..., I_n$ be homogeneous polynomials forming a basis for the invariants of G. Let $d_1, ..., d_n$ be the respective degrees of $I_1, ..., I_n$. Then

(2.4)
$$\prod_{i=1}^{n} d_{i} = |G|, \quad \sum_{i=1}^{n} (d_{i}-1) = r$$

where r = number of reflections in G.

Proof. By Theorem 1.2, $I_1, ..., I_n$ are algebraically independent. Let I(x) be a homogeneous invariant of degree m. Then I is a linear combination of the monomials $I_1^{a_1} ... I_n^{a_n}$ where $a_1 d_1 + ... a_n d_n = m$. Furthermore, these monomials are linearly independent over k, as $I_1, ..., I_n$ are algebraically independent over k. It follows that the dimension δ_m of homogeneous invariants of degree m = number of non-negative integer solutions to $a_1 d_1 + ... + a_n d_n = m$. Hence

(2.5)
$$\sum_{m=0}^{\infty} \delta_m t^m = \frac{1}{(1-t^{d_1}) \dots (1-t^{d_n})}.$$

(1.9) and (2.5) yield

$$(2.6) \frac{1}{|G|} \sum_{\sigma e G} \frac{1}{(1 - \omega_1(\sigma) t) \dots (1 - \omega_n(\sigma) t)} = \frac{1}{(1 - t^{d_1}) \dots (1 - t^{d_n})}$$

Expand both sides of (2.6) in powers of (1-t). Let $\mathcal{R} = \text{set}$ of reflections in G and $\zeta(\sigma) = \text{eigenvalue}$ of the reflection σ which $\neq 1$. We have

(2.7)
$$\frac{1}{|G|} \sum_{\sigma \in G} \frac{1}{(1 - \omega_{1})(\sigma)t) \dots (1 - \omega_{n}(\sigma)t)}$$

$$= \frac{1}{|G|} \frac{1}{(1 - t)^{n}} + \frac{1}{|G|} \sum_{\sigma \in \mathcal{R}} \frac{1}{1 - \zeta(\sigma)} \frac{1}{(1 - t)^{n-1}} + \dots$$
(2.8)
$$\frac{1}{(1 - t^{d_{1}}) \dots (1 - t^{d_{n}})} = \prod_{i=1}^{n} \frac{1}{d_{i}(1 - t) - {d_{i} \choose 2}(1 - t)^{2} + \dots \pm (1 - t)^{d_{i}}}$$

$$= \frac{1}{\prod_{i=1}^{n} d_{i}(1 - t)^{n}} + \frac{\frac{1}{2} \sum_{i=1}^{n} (d_{i} - 1)}{\prod_{i=1}^{n} d_{i}} \frac{1}{(1 - t)^{n-1}} + \dots$$

Equating coefficients of (2.7), (2.8), we get

(2.9)
$$\prod_{i=1}^{n} d_{i} = |G|, \sum_{i=1}^{n} (d_{i}-1) = 2 \sum_{\sigma \in \mathcal{R}} \frac{1}{1-\zeta(\sigma)}.$$

We evaluate the sum

$$\sum_{\sigma \in \mathcal{R}} \frac{1}{1 - \zeta(\sigma)} :$$

Let π be any r.h. Let $H_{\pi} = \{ \sigma \mid \sigma \in G \text{ and } \sigma \text{ fixes } \pi \}$. Thus H_{π} is the subgroup of G consisting of the identity and those reflections in G with r.h. π . Applying Lemma 2.2 to H_{π} , we conclude that there exists $v \notin \pi$ such that $\sigma(v) = \zeta(\sigma)v$ for $\sigma \in H_{\pi}$. Let $H'_{\pi} = H_{\pi} - \{e\}$. Since $\zeta(\sigma^{-1}) = (\zeta(\sigma))^{-1}$, we obtain

(2.10)
$$\sum_{\sigma \varepsilon H_{\pi}^{'}} \frac{1}{1 - \zeta(\sigma)} = \sum_{\sigma \varepsilon H_{\pi}^{'}} \frac{1}{1 - \zeta(\sigma^{-1})}$$

$$= \sum_{\sigma \varepsilon H_{\pi}^{'}} \left(1 - \frac{1}{1 - \zeta(\sigma)}\right) = |H_{\pi}^{'}| - \sum_{\sigma \varepsilon H_{\pi}^{'}} \frac{1}{1 - \zeta(\sigma)}.$$

Hence

(2.11)
$$\sum_{\sigma \in H_{\pi}'} \frac{1}{1 - \zeta(\sigma)} = \frac{|H_{\pi}'|}{2}.$$

Summing both sides of (2.11) over all r.h. π , we get

(2.12)
$$\sum_{\sigma \in \mathcal{R}} \frac{1}{1 - \zeta(\sigma)} = \frac{r}{2} .$$

(2.9), (2.12) yield Theorem 2.2.

THEOREM 2.3. Let $f_1, ..., f_n$ be polynomials in the variables $x_1, ..., x_n$. $f_1, ..., f_n$ are algebraically independent over $k \Leftrightarrow$

$$\frac{\partial (f_1, ..., f_n)}{\partial (x_1, ..., x_n)} \neq 0.$$

Proof. Suppose that $f_1, ..., f_n$ are algebraically independent. Then $G(f_1, ..., f_n) = 0$ for some polynomial $G = G(y_1, ..., y_n)$. Assume that $G(y_1, ..., y_n)$ is of minimal positive degree. Differentiating this relation with respect to x_i , we get

(2.13)
$$\sum_{i=1}^{n} \frac{\partial G}{\partial y_i}(f_1, ..., f_n) \frac{\partial f_i}{\partial x_j} = 0, \ 1 \leqslant j \leqslant n.$$

(2.13) is a system of linear equations (with coefficients in $k(x_1, ..., x_n)$) in the unknowns $H_i(x) = \frac{\partial G}{\partial y_i}(f_1, ..., f_n)$, $1 \le i \le n$. $\frac{\partial G}{\partial y_i} \ne 0$ for some i, as G is not constant, and deg $\frac{\partial G}{\partial y_i} < \deg G$. It follows that the corresponding $H_i(x) \ne 0$. Thus the linear system (2.13) has a non-zero solution, so that its determinant

$$\frac{\partial (f_1, ..., f_n)}{\partial (x_1, ..., x_n)} \neq 0.$$

Conversely, let $f_1, ..., f_n$ be algebraically independent. For each i, $x_i, f_1, ..., f_n$ are algebraically dependent. Hence there exists a polynomial G_i $(x_i, y_1, ..., y_n)$ of minimal positive degree in x_i such that $G_i(x_i, f_1, ..., f_n) = 0$. Differentiating these relations with respect to x_k , we get

(2.14)
$$\sum_{j=1}^{n} \frac{\partial G_{i}}{\partial y_{j}}(x_{i}, f_{1}, ..., f_{n}) \frac{\partial f_{j}}{\partial x_{k}} + \frac{\partial G_{i}}{\partial x_{k}}(x_{i}, f_{1}, ..., f_{n}) \delta_{ik}, 1 \leq k \leq n,$$

 δ_{ik} denoting the Kronecker symbol. (2.14) may be rewritten in matrix notation as

$$\left(\frac{\partial G_i}{\partial y_j}\right) \cdot \left(\frac{\partial f_i}{\partial x_j}\right) = D$$

where the entries of D are

$$-\delta_{ij} \frac{\partial G_i}{\partial x_j}.$$

det $D \neq 0$, as x_i – degree of $\frac{\partial G_i}{\partial x_i} < x_i$ – degree of G_i , $1 \leqslant i \leqslant n$.

It follows from (2.15) that $\frac{\partial (f_1, ..., f_n)}{\partial (x_1, ..., x_n)} \neq 0$.

Theorem 2.4. (Shephard and Todd [19]). Let G be a finite group acting on the n-dimensional space V. Suppose there exists a basis of n homogeneous polynomials for the invariants of G. Then G is a finite reflection group.

Proof. Let H be the subgroup of G generated by the reflections in G. By assumption G has n basic homogeneous invariants which, by Theorem 1.2, are algebraically independent. Since H is a finite reflection group, we conclude from Chevalley's Theorem that H has n basic homogeneous invariants $J_1, ..., J_n$ which are algebraically independent. Each I_i is invariant under H so that $I_i = I_i (J_1, ..., J_n)$, the latter quantity denoting a polynomial in the J_i 's. We may assume that $I_i (J_1, ..., J_n)$ is a linear combination of monomials $J_1^{a_1} ... J_n^{a_n}$ whose x-degree $= \deg I_i$. We have

(2.16)
$$\frac{\partial (I_1, ..., I_n)}{\partial (x_1, ..., x_n)} = \frac{\partial (I_1, ..., I_n)}{\partial (J_1, ..., J_n)} \cdot \frac{\partial (J_1, ..., J_n)}{\partial (x_1, ..., x_n)}$$

By Theorem 2.3,

$$\frac{\partial (I_1, ..., I_n)}{\partial (x_1, ..., x_n)} \neq 0$$

and (2.16) then shows that

$$\frac{\partial (I_1, ..., I_n)}{\partial (J_1, ..., J_n)} \neq 0.$$

It follows that there is a rearrangement $k_1, ..., k_n$ of 1, ..., n so that

$$\frac{\partial I_{k_1}}{\partial J_1} \dots \frac{\partial I_{k_n}}{\partial J_n} \neq 0.$$

Hence $I_{k_i}(J_1, ..., J_n)$ is of positive degree in J_i and $\deg I_{k_i} \geqslant \deg J_i$, $1 \leqslant i \leqslant n$. Applying Theorem 2.2 both to G and H, we obtain

(2.17)
$$\prod_{i=1}^{n} \deg J_{i} = |H|, \prod_{i=1}^{n} \deg I_{i} = |G|$$

(2.18)
$$\sum_{i=1}^{n} (\deg J_i - 1) = \sum_{i=1}^{n} (\deg I_i - 1) = r$$

where r = number of reflections in G = number of reflections in H.

Since $\deg I_{k_i} \geqslant \deg J_i$, $1 \leqslant i \leqslant n$, we conclude from (2.18) that $\deg I_{k_i} = \deg J_i$, $1 \leqslant i \leqslant n$. Hence $\prod_{i=1}^n \deg I_i = \prod_{i=1}^n \deg J_i$, and we conclude from (2.17) that |G| = |H|. Thus G = H and G is a finite reflection group.

3. A FORMULA FOR
$$\frac{\partial (I_1, ..., I_n)}{\partial (x_1, ..., x_n)}$$

We obtain a formula which shall be used in Chapter III.

THEOREM 2.5. Let G be a finite reflection group acting on the n-dimensional space V. Let $I_1, ..., I_n$ be a basic set of homogeneous invariants for G. Let x be a coordinate system for V and $L_i(x) = 0, 1 \le i \le r$, the r.h.'s for G, each L_i being linear and homogeneous. Then

(2.19)
$$\frac{\partial (I_1, ..., I_n)}{\partial (x_1, ..., x_n)} = c \prod_{i=1}^r L_i(x)$$

c being a constant $\neq 0$.

Proof. Let J the left hand side of (2.19). We observe that J is a non-zero homogeneous polynomial of degree $\sum_{i=1}^{n} (d_i - 1)$. By Theorem 2.2, $\sum_{i=1}^{n} (d_i - 1) = r$, so that deg J = r. If k is the real field R, we have the following simple proof of (2.19). $I_i = I_i(x_1, ..., x_n)$, $1 \le i \le n$, is a mapping from x-space to I-space. This mapping is not 1 - 1 in any neighborhood of a point x lying in the r.h. $L_i(x) = 0$, as any point and its reflection get mapped into the same point I. It follows from the Implicit Function Theorem that J(x) = 0, whenever $L_i(x) = 0$. Thus $L_i \mid J$, $1 \le i \le r$, and so $\prod_{i=1}^{r} L_i \mid J$. Since J, $\prod_{i=1}^{r} L_i$ have the same degree r, we have $J = c \prod_{i=1}^{r} L_i$, $c \ne 0$.

For an arbitrary field k, the theorem is proven as follows. Let π be an r.h. with equation L(x)=0 and H the subgroup of h elements in G fixing π . Thus there are h-1 reflections in G with r.h. π . We show that $L^{h-1} \mid J$. By Lemma 2.2, H is a cyclic group generated by an element σ . Furthermore there exists $v \notin \pi$ and a primitive h-th root of 1 such that $\sigma(v)=\zeta v$. Choose a coordinate system $y=(y_1,...,y_n)$ in V so that π has the equation $y_n=0$ and v=(0,...,0,1) σ then becomes the transformation $(y_1,...,y_{n-1},y_n) \to (y_1,...,y_{n-1},\zeta y_n)$. Let $x=\tau y$ and $J_i(y)=I_i(\tau y), 1 \leqslant i \leqslant n$. We have

$$(2.20) J_i(y_1, ..., y_{n-1}, \zeta y_n) = J_i(y_1, ..., y_{n-1}, y_n), \ 1 \le i \le n$$

Let $J_i = \sum A_m y_n^m$, the A_m 's being polynomials in $y_1, ..., y_{n-1}$. (2.20) implies that $A_m = 0$ whenever $h \nmid m$, so that $A_m = 0$, $0 \le m \le h - 1$. Since

$$\frac{\partial J_i}{\partial y_m} = \Sigma_m A_m y_n^{m-1},$$

we conclude

$$y_n^{h-1} \left| \frac{\partial J_i}{\partial y_n}, 1 \leqslant i \leqslant n \right|.$$

Hence

(2.21)
$$y_n^{h-1} \left| \frac{\partial (J_1, ..., J_n)}{\partial (y_1, ..., y_n)} \right|,$$

Since

$$\frac{\partial (J_1, ..., J_n)}{\partial (y_1, ..., y_n)} = J(x) \cdot \det \tau,$$

(2.21) is equivalent to $L^{h-1}(x) \mid J(x)$. It follows that if $L_i(x) = 0$, $1 \le i \le r$, are the r.h.'s for G, then $\prod_{i=1}^r L_i \mid J$. But J, $\prod_{i=1}^r L_i$ have the same degree r, so that $J = c \prod_{i=1}^r L_i c \ne 0$.

4. Decomposition of Finite Reflection Groups

We shall decompose every finite reflection group into a direct product of irreducible ones and show that it suffices to study the invariant theory of the irreducible groups.

DEFINITION 2.3. Let the group G act on V. G is said to be reducible iff there exists a proper subspace W invariant under G; i.e. $\sigma w \in W$ for $\sigma \in G$, $w \in W$. G is said to be completely reducible iff $V = V_1 \oplus V_2$, V_1 and V_2 being proper invariant subspaces. G is said to be irreducible iff it is not reducible.

Theorem 2.6. (Maschke [22], Vol. 2, p. 179). Let G be a finite group acting on the vector space V. If G is reducible, then it is completely reducible.

Proof. Let V_1 be a proper invariant subspace of V. Let V_2 be a complementary subspace. Thus for $v \in V$, we have a unique decomposition

 $v = v_1 + v_2, v_i \in V_i$ (i = 1, 2). Let $\eta v = v_2$ and set $\tau = \frac{1}{|G|} \sum_{\sigma \in G} \sigma \eta \sigma^{-1}$. τ satisfies the following:

i)
$$\tau \sigma = \sigma \tau$$
, $\sigma \in G$. For $\sigma \tau = \frac{1}{|G|} \sum_{\sigma_1 \in G} \sigma \sigma_1 \eta (\sigma \sigma_1)^{-1} \sigma = \tau \sigma$

- ii) $\tau v_1 = 0$, $v_1 \in V_1$. For $\sigma^{-1} v_1 \in V_1$, $\sigma \in G$, so that $\eta \sigma^{-1} v_1 = 0$ $\Rightarrow \tau v_1 = 0$
- iii) $(1-\tau)$ $v \in V_1$, $v \in V$, 1 denoting the identity of G. For $(1-\eta)$ $v \in V_1$, so that $(1-\eta)$ σ^{-1} $v \in V_1$ $\Rightarrow \sigma$ $(1-\eta)$ σ^{-1} $v \in V_1$, $\sigma \in G$. It follows that $(1-\tau)$ $v = \frac{1}{\mid G \mid} \sum_{\sigma \in G} \sigma (1-\eta) \sigma^{-1} v \in V_1$.

Let $V_2' = \tau V$. V_2' is invariant under G as $\sigma(\tau v) = \tau(\sigma v)$. For any v, $v = \tau v + (1-\tau)v$. It follows from iii) that $V = V_1 + V_2'$. ii), iii) imply $\tau(1-\tau) = 0 \Leftrightarrow \tau = \tau^2$. Hence $\tau v_2' = v_2'$ for $v_2' \in V_2'$. Let $v_1 + v_2' = 0$, where $v_1 \in V_1$, $v_2' \in V_2'$. Applying τ to both sides, we get $v_2' = 0$ and so $v_1 = 0$. Hence $V = V_1 \oplus V_2'$.

Repeated application of Maschke's Theorem yields the

COROLLARY. Let G be a finite group acting on the finite-dimensional vector space V. Then $V = V_1 \oplus ... \oplus V_s$, the V_i 's being invariant subspaces of V and G acting irreducibly on each V_i .

For finite reflection groups, we have

Theorem 2.7. Let G be a finite reflection group acting on V. There exists a decomposition $V=V_1\oplus\ldots\oplus V_s$ into invariant subspaces such that:

- 1) Let $G_i = G|_{V_i} = \text{group of restrictions of elements of } G \text{ to } V_i$. Then G is isomorphic to $G_1 \times ... \times G_s$
- 2) Each G_i , $1 \le i \le s$, is a reflection group acting irreducibly on V_i .

Proof. By the corollary to Theorem 2.6, there exists a decomposition $V = V_1 \oplus ... \oplus V_s$, the V_i 's being invariant subspaces and G_i irreducible for $1 \le i \le s$. We label the V_i 's so that $V_1, ..., V_r$ are 1-dimensional and $G|_{V_i} = \text{identity}$.

By the remark following Definition 2.1, for each reflection σ there exists an eigenvector $v \in V - \pi$, π being the r.h. for σ . Call v a root of G. We have

$$(2.22) \qquad \dim (V_i + \pi) + \dim (V_i \cap \pi) = \dim V_i + \dim \pi.$$

If $V_i \not = \pi$, then $V_i + \pi = V$ and we conclude from (2.22) that dim V_i = dim $(V_i \cap \pi) + 1$. I.e. $V_i \cap \pi$ is a hyperplane in V_i and $\sigma |_{V_i}$ a reflection on V_i . Choose $u \in V_i - \pi$ so that u is an eigenvector of σ . u is a multiple of the root v, so that $v \in V_i$. Thus $\sigma |_{V_i}$ is a reflection of V_i if $v \in V_i$, and the identity if $v \notin V_i$. Furthermore, each root v is in some V_i , $v \in V_i$, otherwise the corresponding reflection σ would have been the identity.

Let G_i = subgroup generated by those reflections whose roots are in V_i , $1 \le i \le s$. It is readily checked that $G = G_1 \times ... \times G_s$, $G_i = G_i \mid_{V_i}$. If $\sigma \in G_i$ and $\sigma \mid_{V_i} = identity$ then $\sigma = identity$. The mapping $\sigma \to \sigma \mid_{V_i}$ is thus an isomorphism from G_i onto G_i .

Theorem 2.8. Let G be a finite reflection group acting on V and decompose V as in Theorem 2.7. Every polynomial invariant under G is a polynomial in the invariant polynomials of $G_1, ..., G_s$.

Proof. For each $v \in V$, write $v = v_1 + ... + v_s$, $v_i \in V_i$. By Theorem 2.7, for each $\sigma \in G$, we may write $\sigma v = \sigma_1 v_1 + ... + \sigma_s v_s$, $\sigma_i \in G_i$. For any polynomial function p(v) on V, we have $p(v) = \sum_{i=1}^{N} p_{i1}(v_1) ... p_{is}(v_s)$ where $p_{ij}(v_j)$ is a polynomial function on V_j . If p(v) is invariant under G, then

(2.23)
$$p(v) = \frac{1}{|G|} \sum_{\sigma \in G} p(\sigma v) = \sum_{i=1}^{N} I_{i1}(v_1) \dots I_{is}(v_s)$$

where

$$(2.24) I_{ij}(v_j) = \frac{1}{|G_j|} \sum_{\sigma_j \in G_j} p_{ij}(\sigma_j v_j)$$

is an invariant of G_j .

CHAPTER III

THE DEGREES OF THE BASIC INVARIANTS

We determine the degrees of the basic homogeneous invariants in case G is a finite reflection group. We present two different methods. The first one (Theorem 3.8), restricts itself to the case where k is the real field and has the advantage of providing an effective method for computing the